

ON THE DEVELOPMENT OF NUMERICAL TECHNIQUE OF ROTOR AERACOUSTICS AND AERODYNAMICS CHARACTERISTICS IN FORWARD FLIGHT

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FIFTH INTERNATIONAL WORKSHOP

COMPUTATIONAL
EXPERIMENT
IN AEROACOUSTICS



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OUTLINE

MOTIVATION

I MATHEMATICAL MODEL AND NUMERICAL METHOD

II ROADMAP OF MODELS

III VALIDATION

1. Caradonna-Tung problem
2. KAI scaled main rotor

VI APPLICATION

1. Kamov shrouded rotor (hover)
2. Kamov scaled main rotor (hover)
3. Pavlov scaled main rotor (forward flight)

V CONCLUSION

Robust computational techniques for rotor
aerodynamics and **acoustic** characteristics evaluation
are required

“**Robust**” – compromise between acceptable accuracy
and available resources



MATHEMATICAL MODEL AND NUMERICAL METHOD

Mathematical model and numerical method

$$\frac{\partial \mathbf{Q}}{\partial t} + \frac{\partial \mathbf{F}(\mathbf{Q})}{\partial x} + \frac{\partial \mathbf{G}(\mathbf{Q})}{\partial y} + \frac{\partial \mathbf{H}(\mathbf{Q})}{\partial z} = \frac{1}{Re} \left(\frac{\partial \mathbf{F}_\nu(\mathbf{Q})}{\partial x} + \frac{\partial \mathbf{G}_\nu(\mathbf{Q})}{\partial y} + \frac{\partial \mathbf{H}_\nu(\mathbf{Q})}{\partial z} \right)$$

\mathbf{Q} – vector of full or linearized conservative variables

$\mathbf{F}, \mathbf{G}, \mathbf{H}$ – vectors of full or linearized conservative fluxes

$\mathbf{F}_\nu, \mathbf{G}_\nu, \mathbf{H}_\nu$ – vectors of dissipative fluxes, Re – Reynolds number



NOISEtte

Family of Euler-based models

- EE – full Euler equations
- NSE – full Navier-Stokes equations

Near field

Turbulence models

- RANS, URANS (SA, K-Epsilon, K-Omega, SST Menter)
- DES, DDES, IDDES

Far field

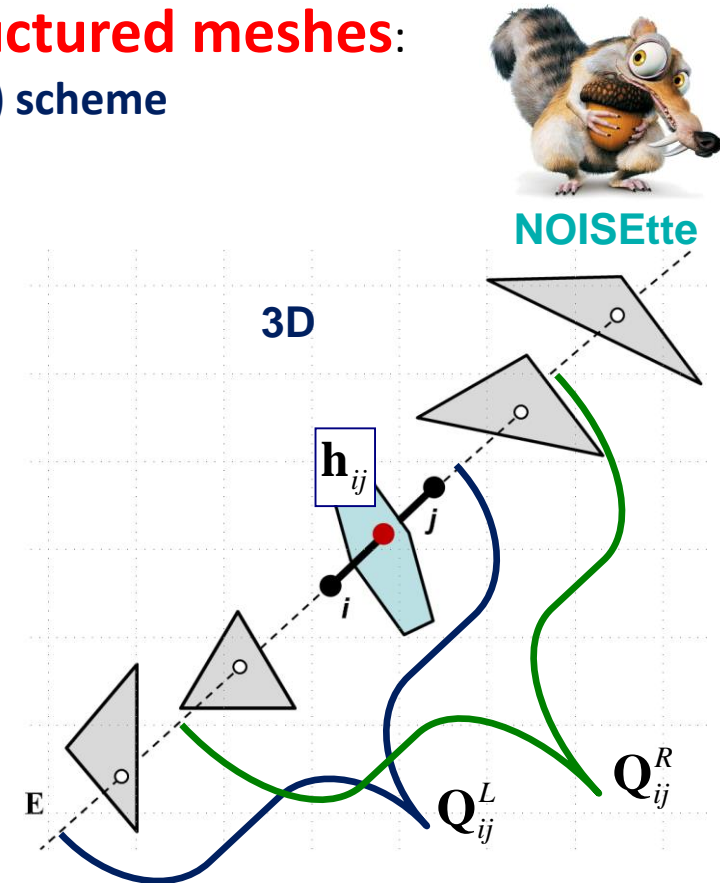
Far field acoustics – FW/H («1A» Farassat formulation)

Mathematical model and numerical method

Higher-accuracy schemes on unstructured meshes: Quasi-1D EBR (Edge-Based Reconstruction) scheme

The basic idea is quasi-1D reconstruction

- 1) FV approximation of NS convective terms
- 2) Godunov-type numerical fluxes as the function of **reconstructed** gas dynamic variables
- 3) edge-based direction “pierces” the mesh and finds the points of intersection of it with faces from both sides of the endpoints of the parent edge ij
- 4) values in 1D-stencil points are calculated by the linear interpolations on intersecting faces



Navier-Stokes equations in rotating frame reference

$$\mathbf{V} = \boldsymbol{\omega} \times \mathbf{r}$$



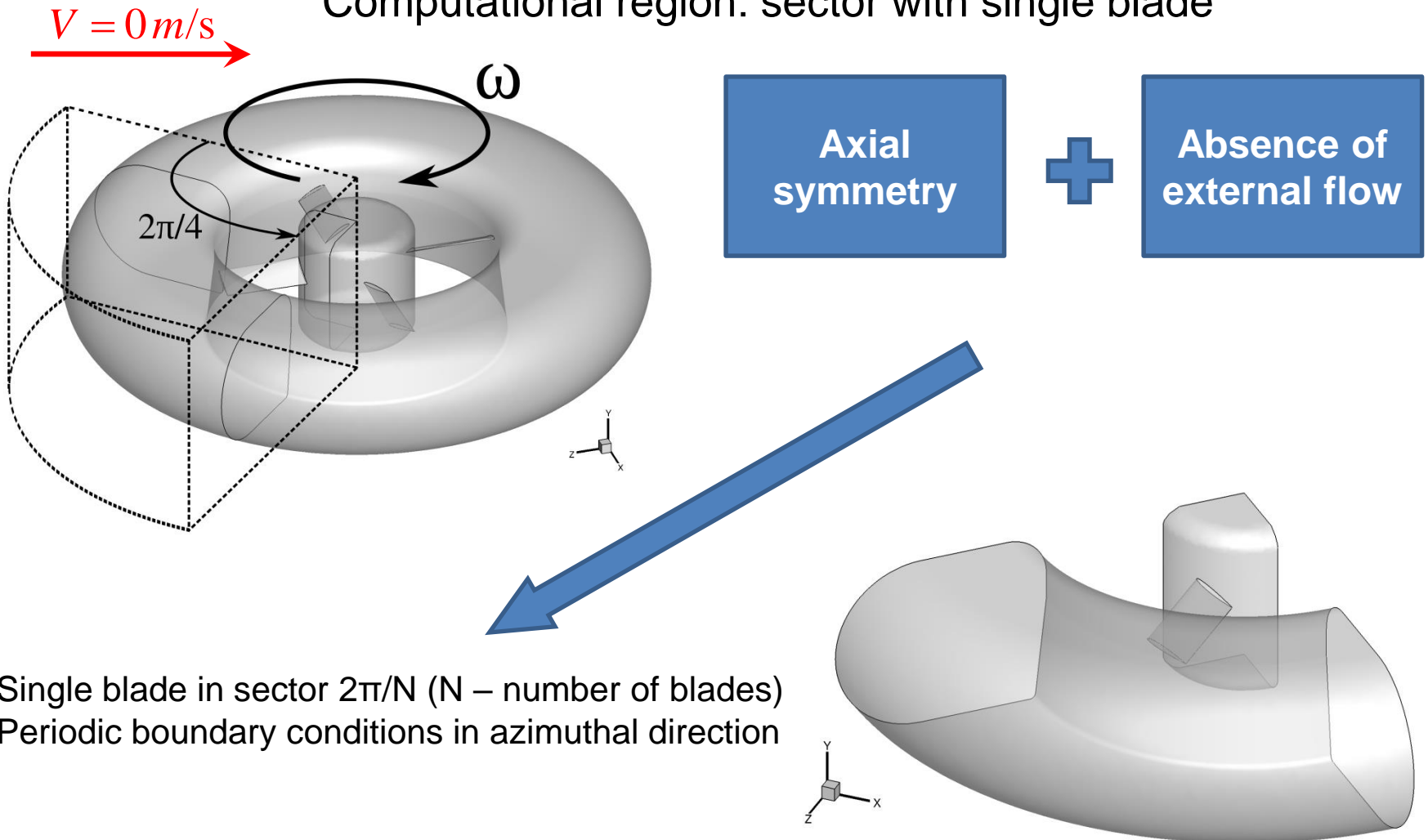
NOISEtte

$$\left\{ \begin{array}{l} \frac{\partial \rho}{\partial t} + \operatorname{div} \rho(\mathbf{u} - \mathbf{V}) = 0 \\ \frac{\partial \rho \mathbf{u}}{\partial t} + \operatorname{Div} \rho(\mathbf{u} - \mathbf{V}) \otimes \mathbf{u} + \nabla p = \operatorname{Div} \mathbf{S} - \rho(\boldsymbol{\omega} \times \mathbf{u}) \\ \frac{\partial E}{\partial t} + \operatorname{div}(\mathbf{u} - \mathbf{V}) E + \operatorname{div} \mathbf{u} p = \operatorname{div} \mathbf{q} + \operatorname{div} \mathbf{S} \mathbf{u} \end{array} \right.$$

Mathematical model and numerical method

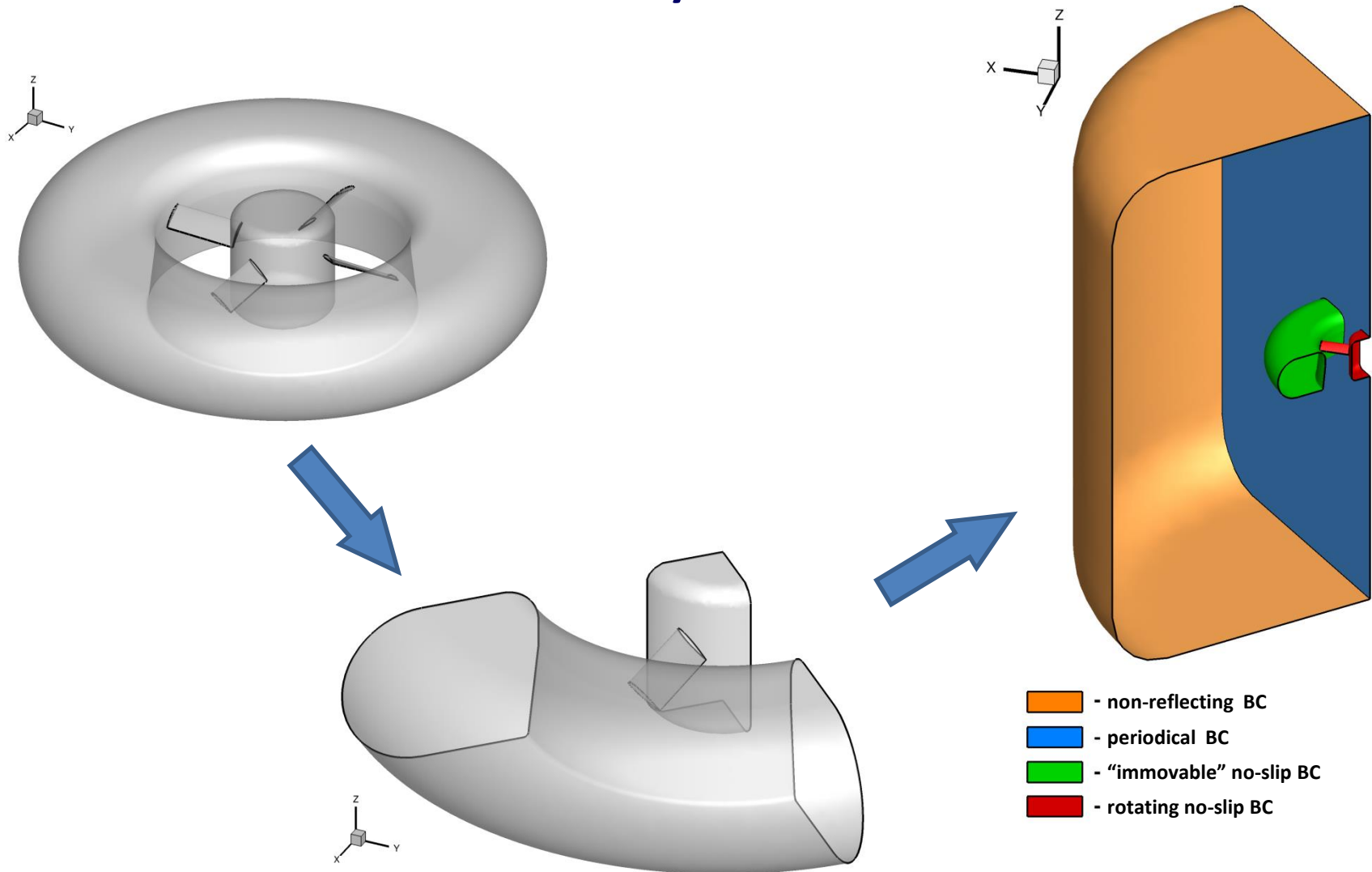
Single sector modeling

Computational region: sector with single blade



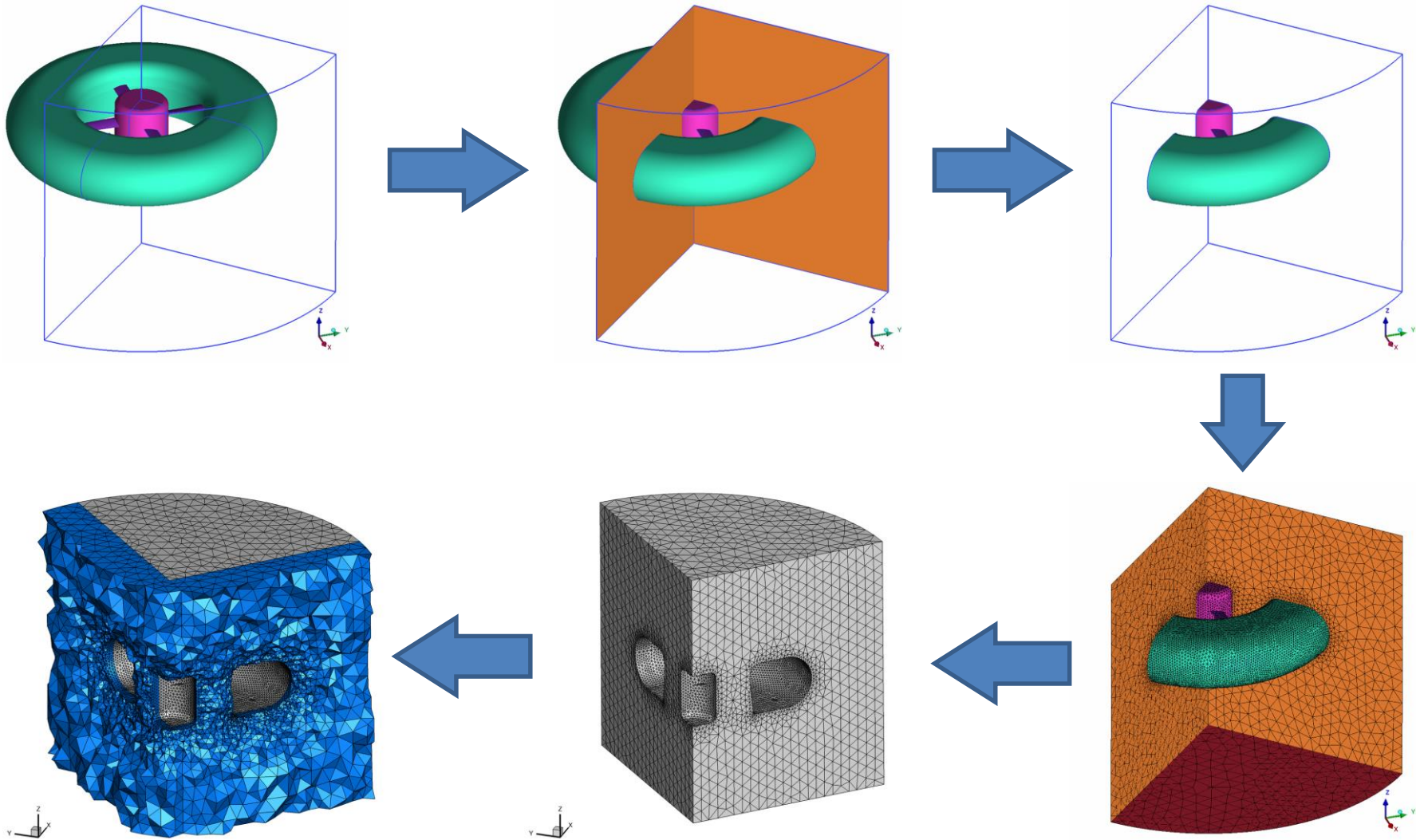
Mathematical model and numerical method

Boundary conditions



Mathematical model and numerical method

Single sector with blade: meshing



Roadmap of Models

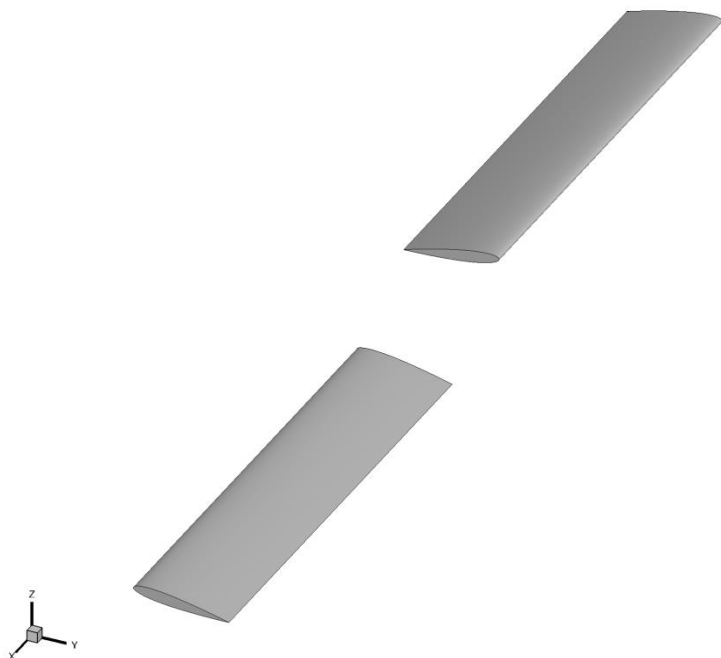
Flight mode	Properties	Sector	EE	RANS	DES
Hovering, vertical climbing, slow descent (with negligible blade-vortex interaction effects)	Thrust	+	+	+	+
	Torque	+	—	+	+
	Tonal noise	+	+	+	+
	Broadband noise	+	—	—	+
Descent	Thrust	+	+	+	+
	Torque	+	—	+	+
	Tonal noise	+	+	+	+
	Broadband noise	±	—	—	+
Cruising fight	Thrust	—	+	+	+
	Torque	—	—	+	+
	Tonal noise	—	+	+	+
	Broadband noise	—	—	—	+

VALIDATION

CARADONNA-TANG¹ ROTOR

¹ Caradonna, F.X. and Tung, C. Experimental and Analytical Studies of a Model Helicopter Rotor in Hover. Technical report, NASA Technical Memorandum TM-81232, 1981

Caradonna-Tang: problem setup



Blades count N	2
Rotor radius R	1.143 m
Blade chord b	0.1905 m
Blade base profile	NACA 0012
Pitch angle	8°
Rotation speed	650 RPM
Blade tip velocity V_{tip}	77.8 m/s

$$\rho_0 = 1.2041 \text{ kg/m}^3, \mu_0 = 1.827 \times 10^{-5} \text{ N} \cdot \text{cm/m}^2$$

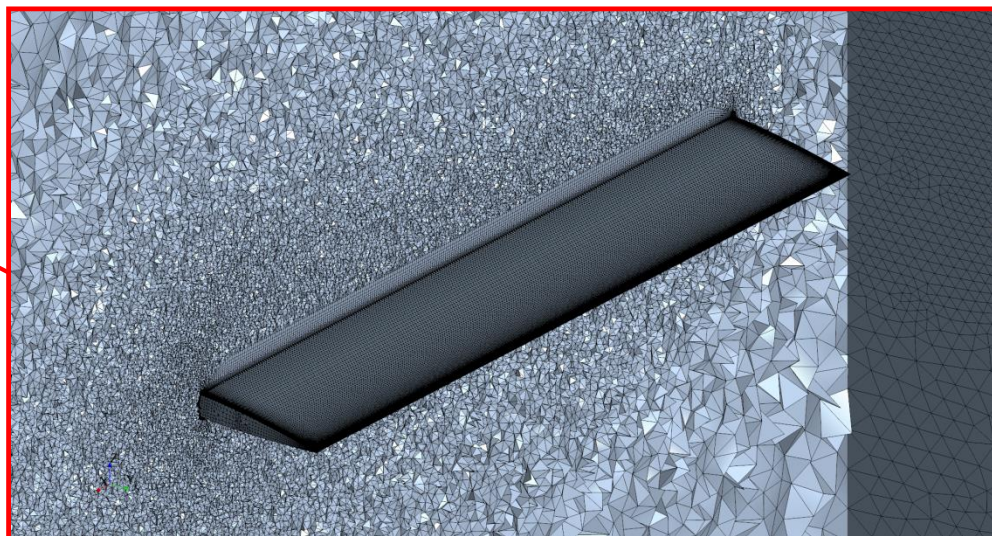
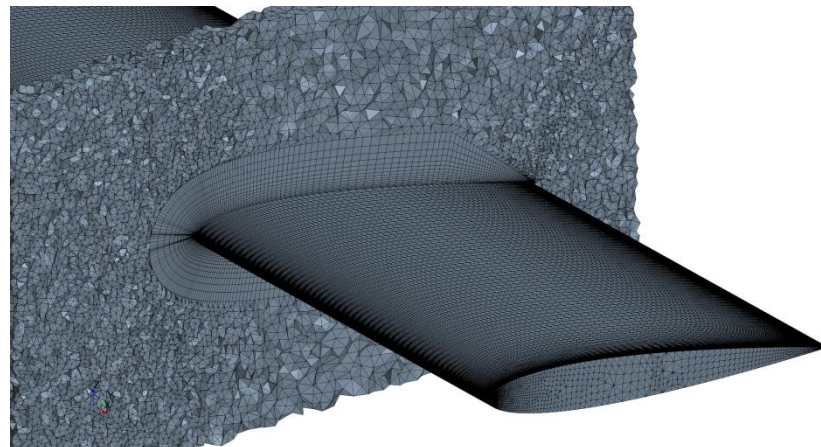
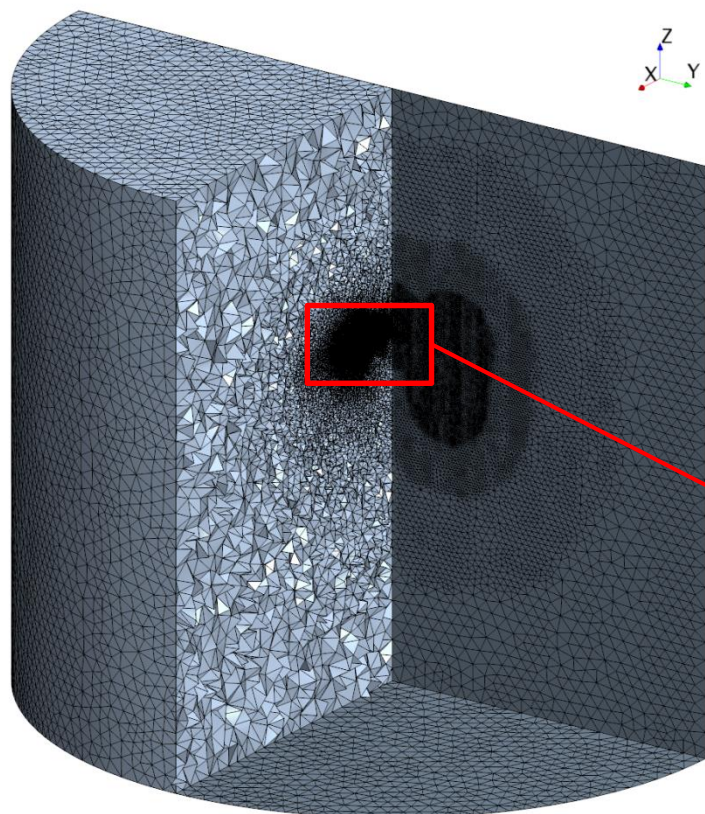
$$\text{Re} = \frac{\rho_0 V_{tip} b}{\mu_0} = 6.28 \times 10^5$$

Caradonna-Tang: mesh

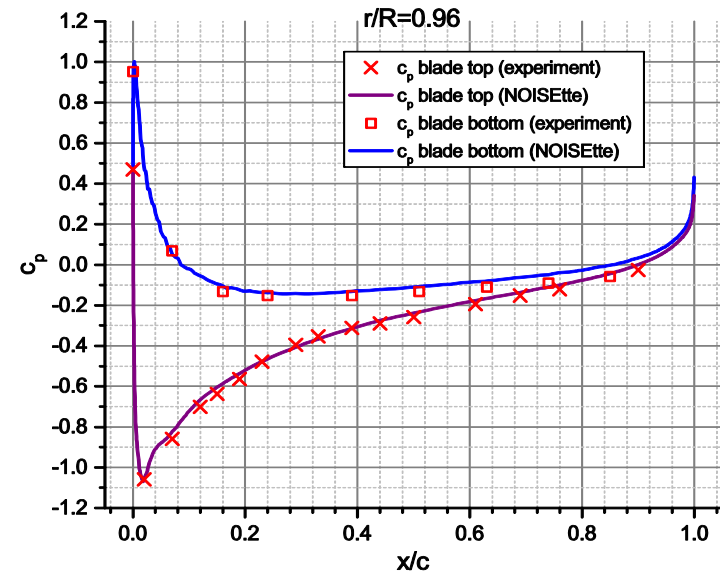
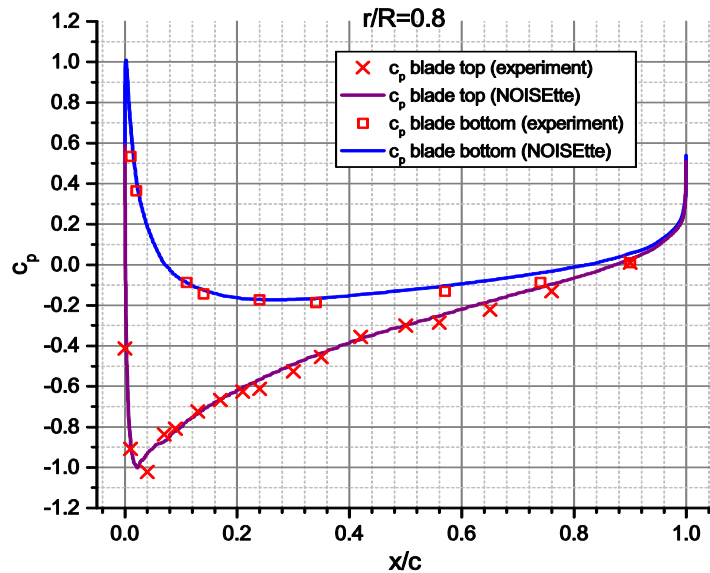
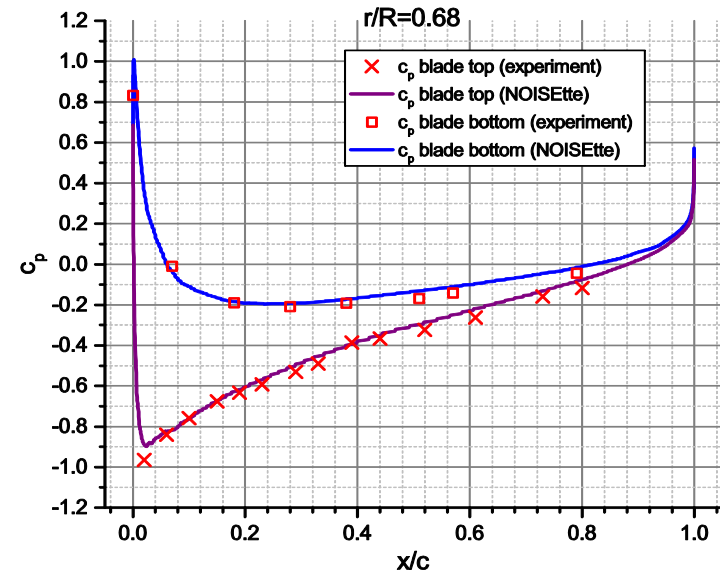
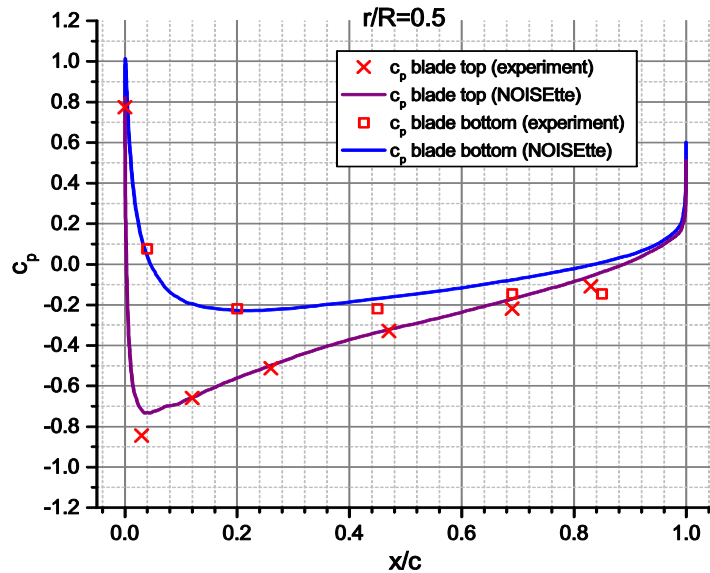
Hybrid mesh:

7 039 966 nodes

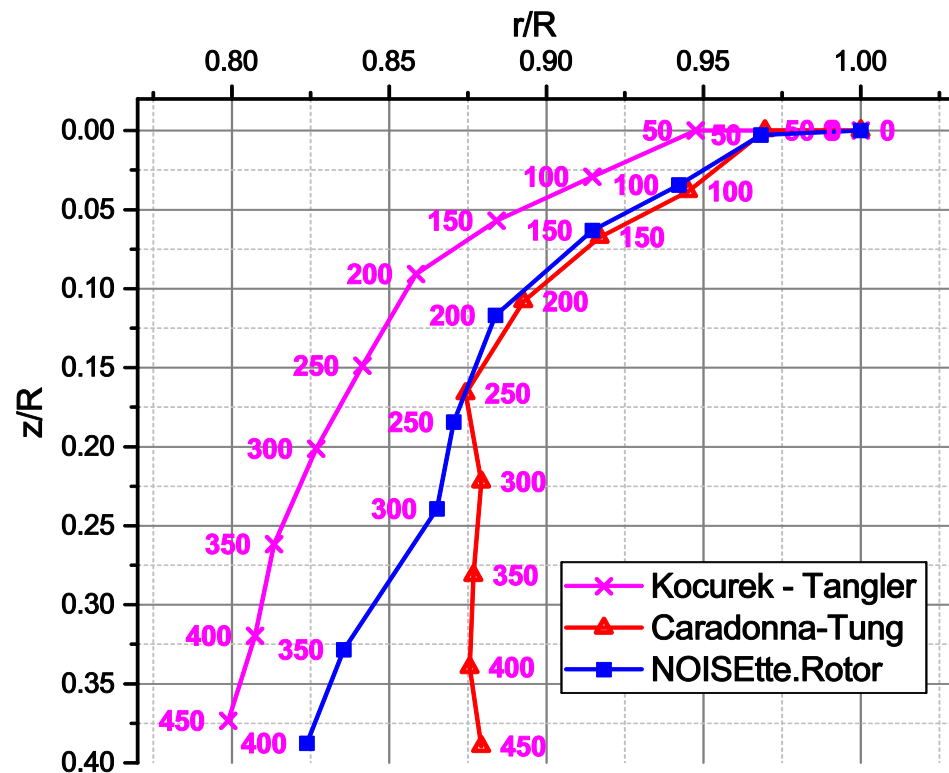
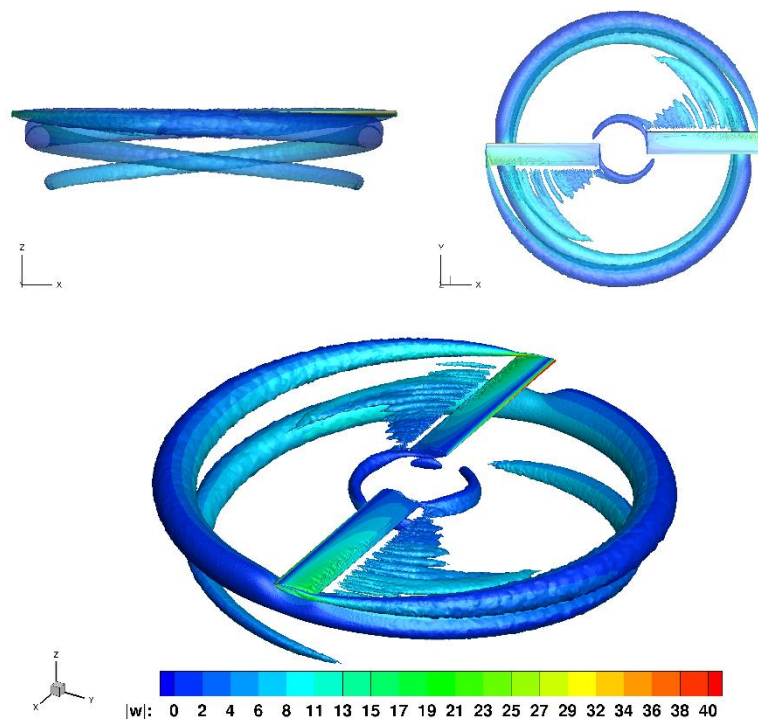
37 526 305 cells



Caradonna-Tang: pressure coefficient



Caradonna-Tang: tip vortex evolution

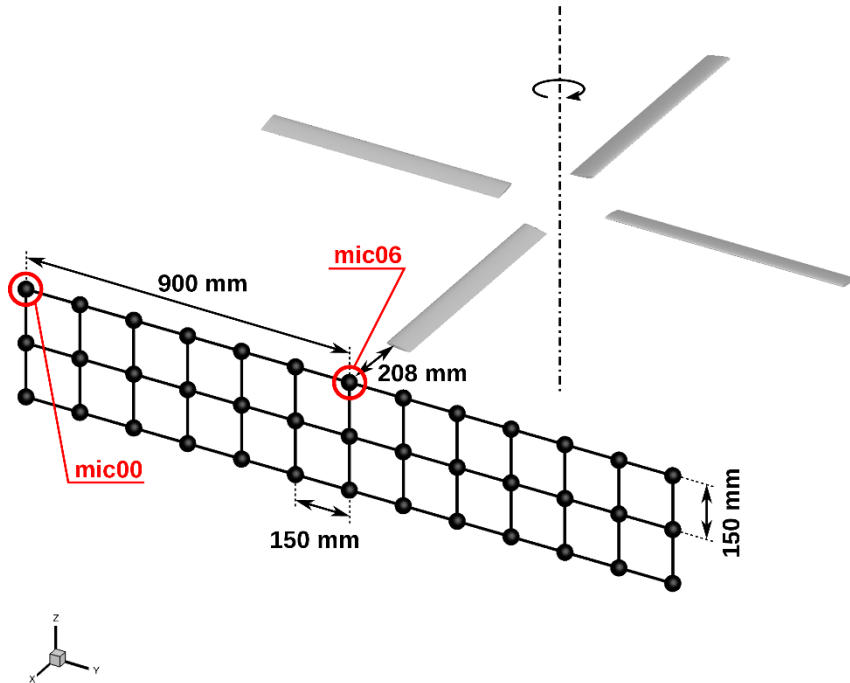


Tip vortex horizontal and vertical displacement



KAI SCALED MAIN ROTOR

KAI scaled main rotor: problem setup



Blades count N	4
Rotor radius R	0.8 m
Blade chord b	0.065 m
Blade base profile	NACA 0012
Pitch angle	8°
Rotation speed	1100 RPM
Blade tip velocity V_{tip}	92.4 m/s

$$\rho_0 = 1.193 \text{ kg/m}^3, \mu_0 = 1.822027 \times 10^{-5} \text{ N} \cdot \text{s/m}^2$$

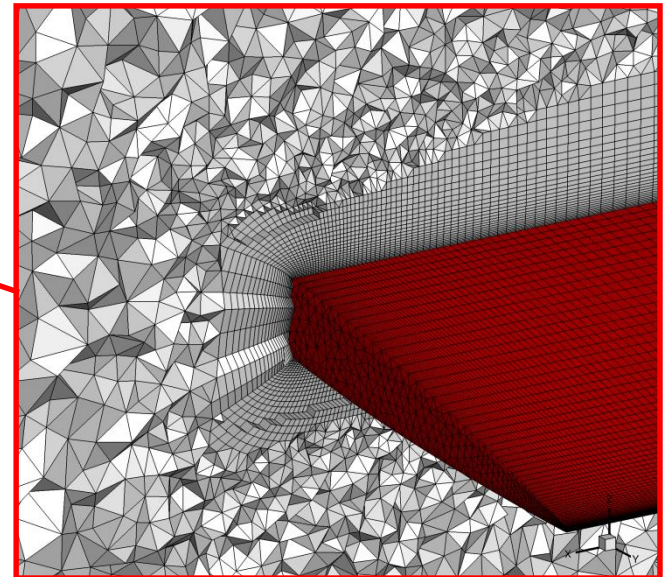
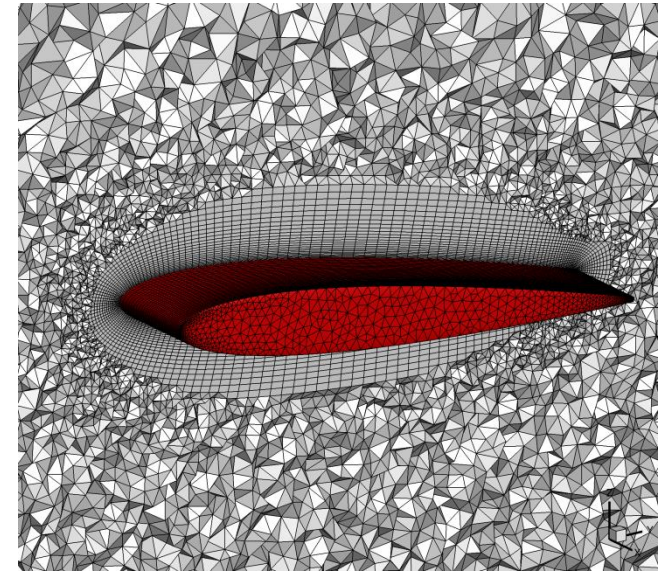
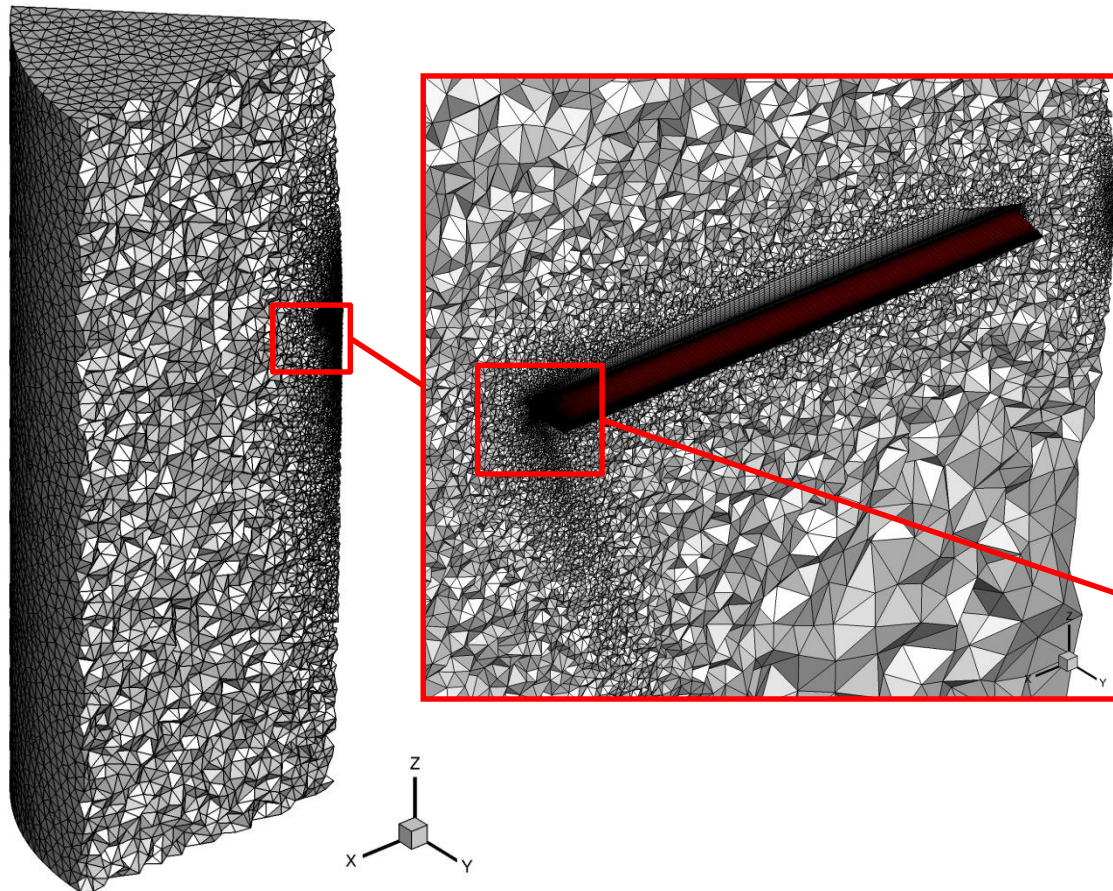
$$\text{Re} = \frac{\rho_0 V_{tip} b}{\mu_0} \approx 1.4 \times 10^6$$

KAI scaled main rotor: mesh

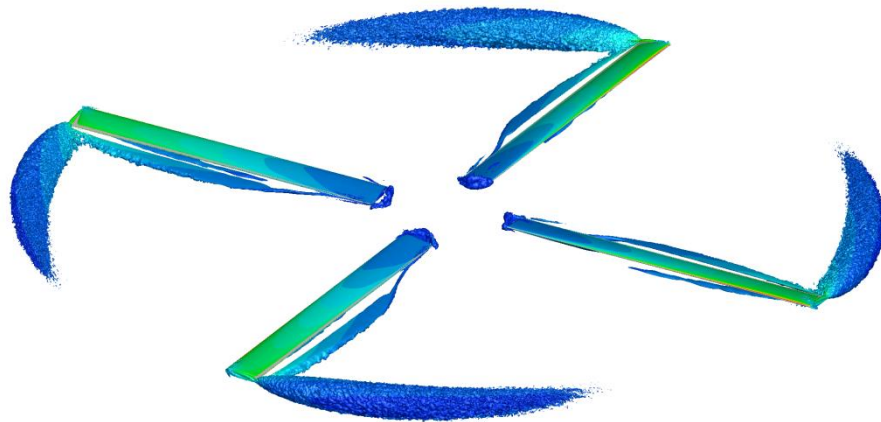
Hybrid mesh:

4 740 520 nodes

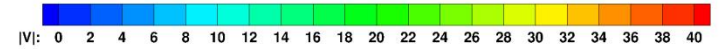
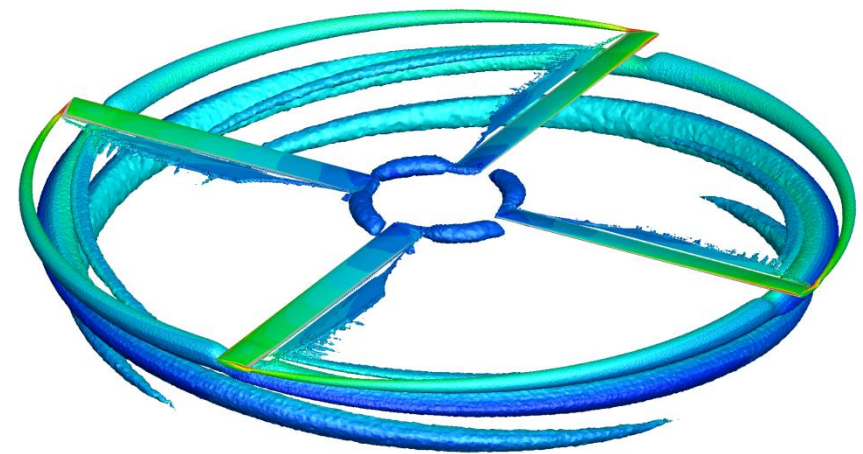
17 575 980 cells



KAI scaled main rotor: order and accuracy

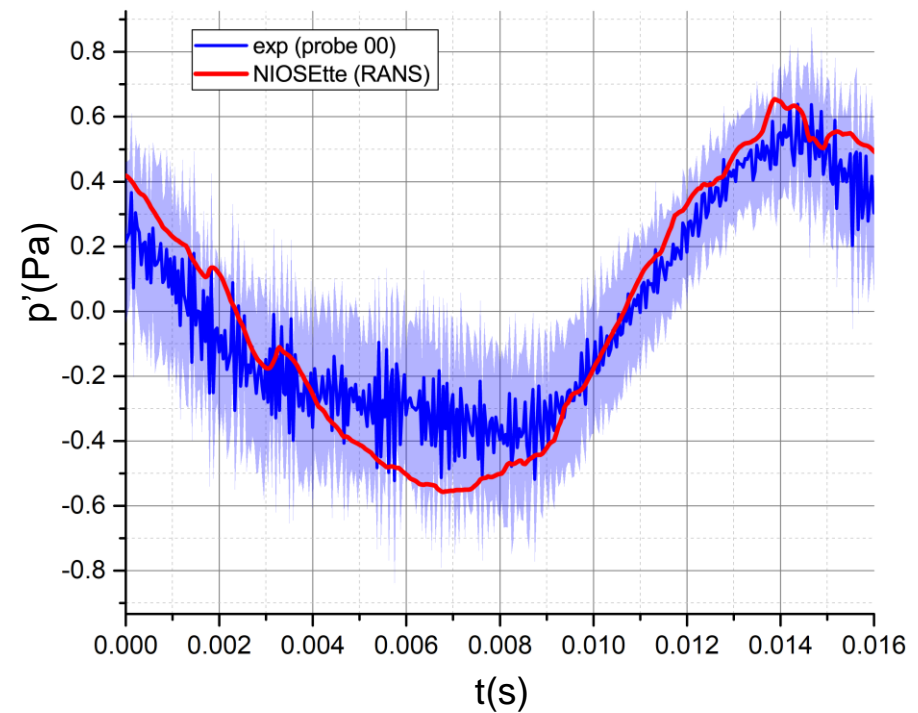
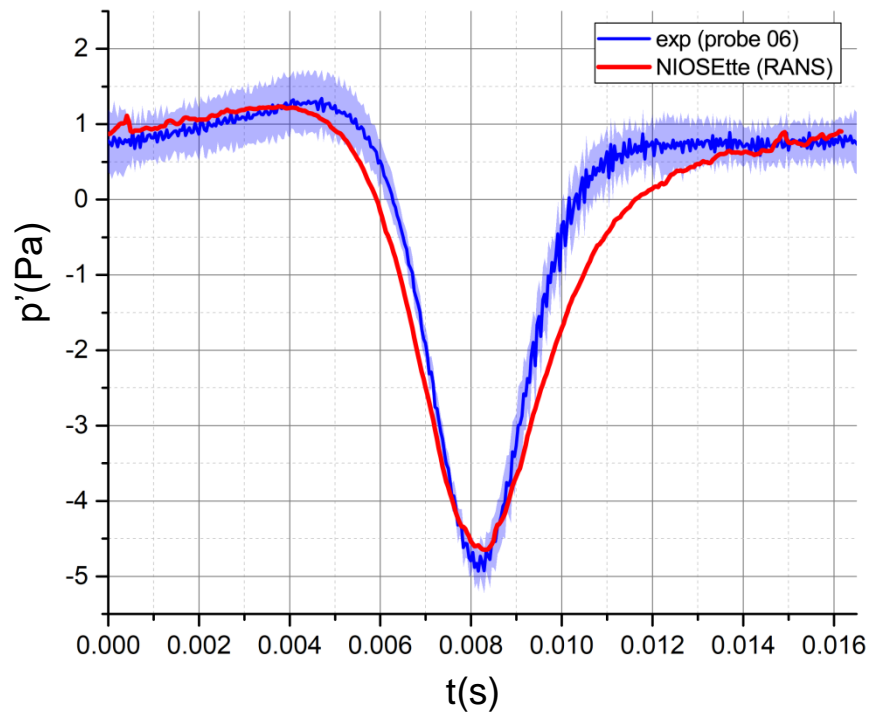


1st order



EBR3

KAI scaled main rotor: near field acoutics



Pressure pulsations in probe mic06 (left) and mic00(right)

APPLICATION

KAMOV SHROUDED ROTOR

Kamov shrouded rotor: problem setup



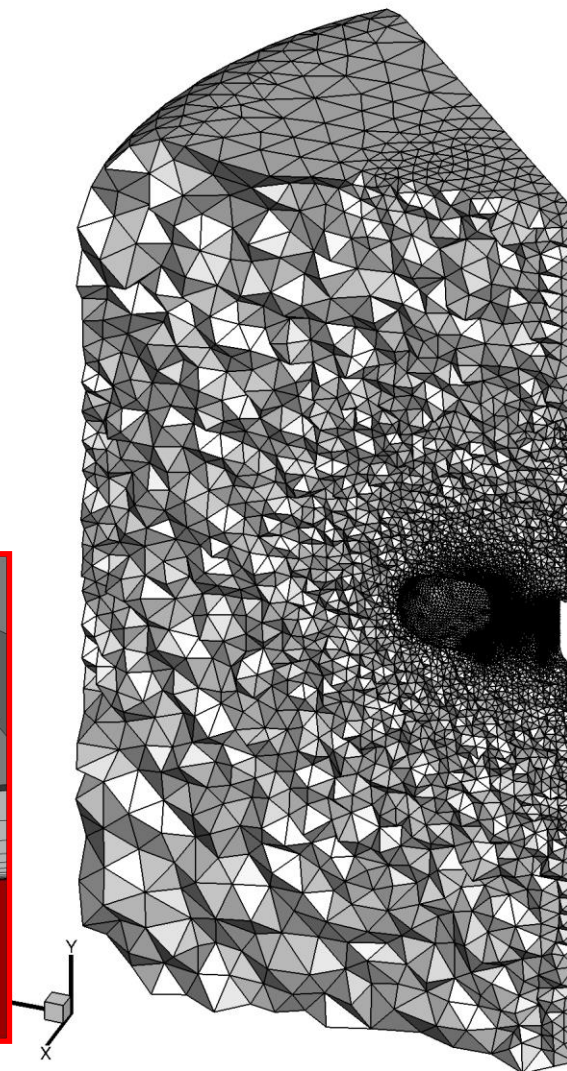
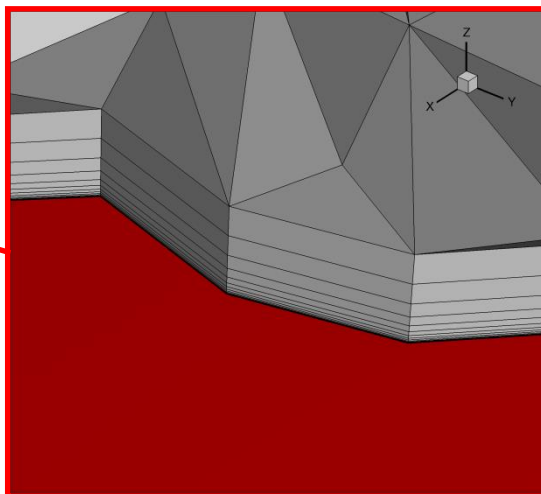
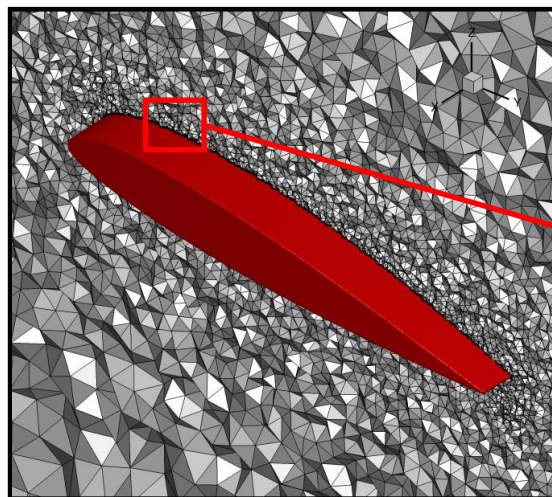
Blades count N	4
Rotor radius R	1.2 m
Blade chord b	0.13 m
Hub radius	0.248 m
Blade base profile	TSAGI SV-11
Blade twist	linear, $\varphi(r) = \frac{40}{3} \left(0.7 - \frac{r}{0.6} \right)$
Channel inner radius	0.605 m
Channel outer radius	1.25 m
Rotation speed	1166.4 RPM
Blade tip velocity V_{tip}	73.3 m/s

$$\rho_0 = 1.2041 \text{ kg/m}^3, \mu_0 = 1.827 \times 10^{-5} \text{ N} \cdot \text{s/m}^2$$

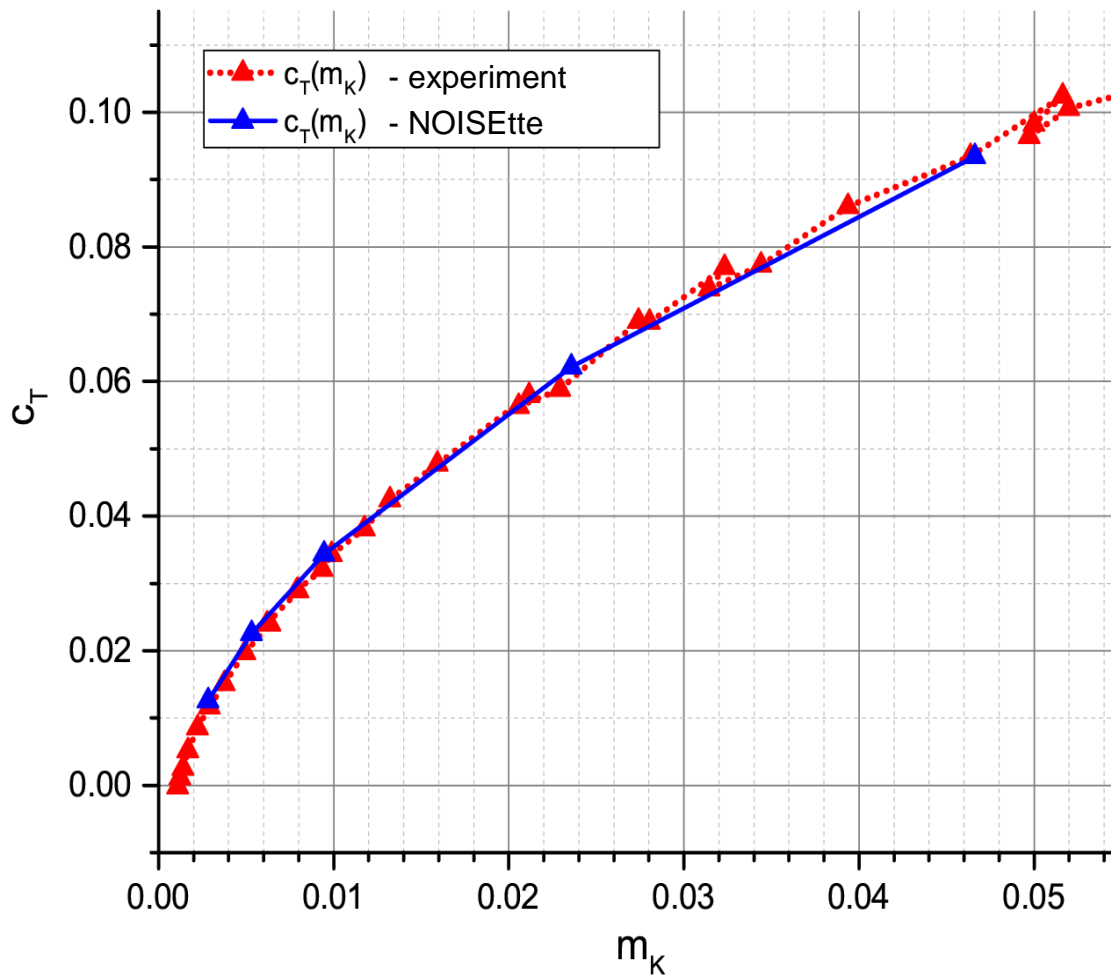
$$\text{Re} = \frac{\rho_0 V_{\text{non}} b}{\mu_0} = 6.28 \times 10^5$$

Kamov shrouded rotor: meshes

Pitch angle	Nodes count	Cells count
10°	2 326 941	13 589 791
15°	2 371 707	13 859 009
15° (Hybrid)	2 374 581	7 352 927
20°	2 511 582	14 669 900
30°	2 555 652	14 936 402
30° (Hybrid fine)	6 478 232	21 016 355
40°	2 592 469	15 154 418

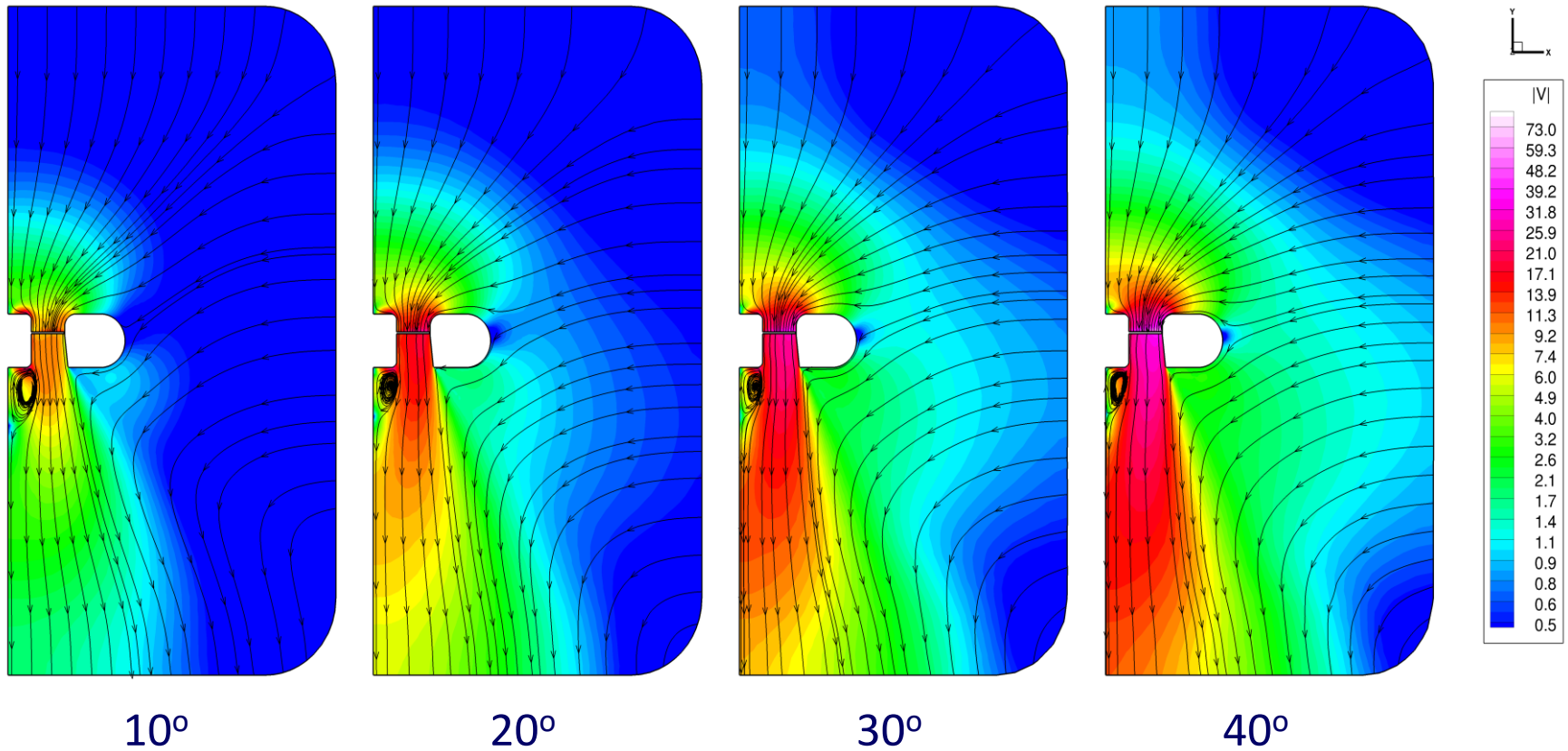


Kamov shrouded rotor: aerodynamics



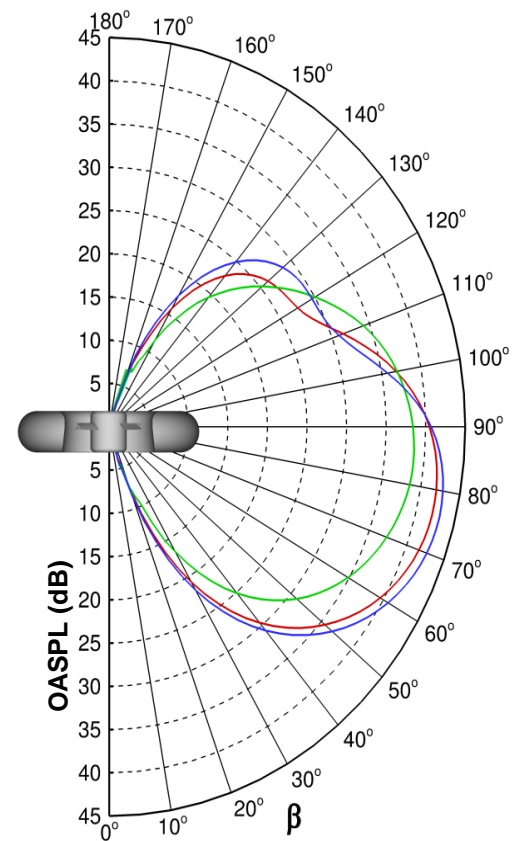
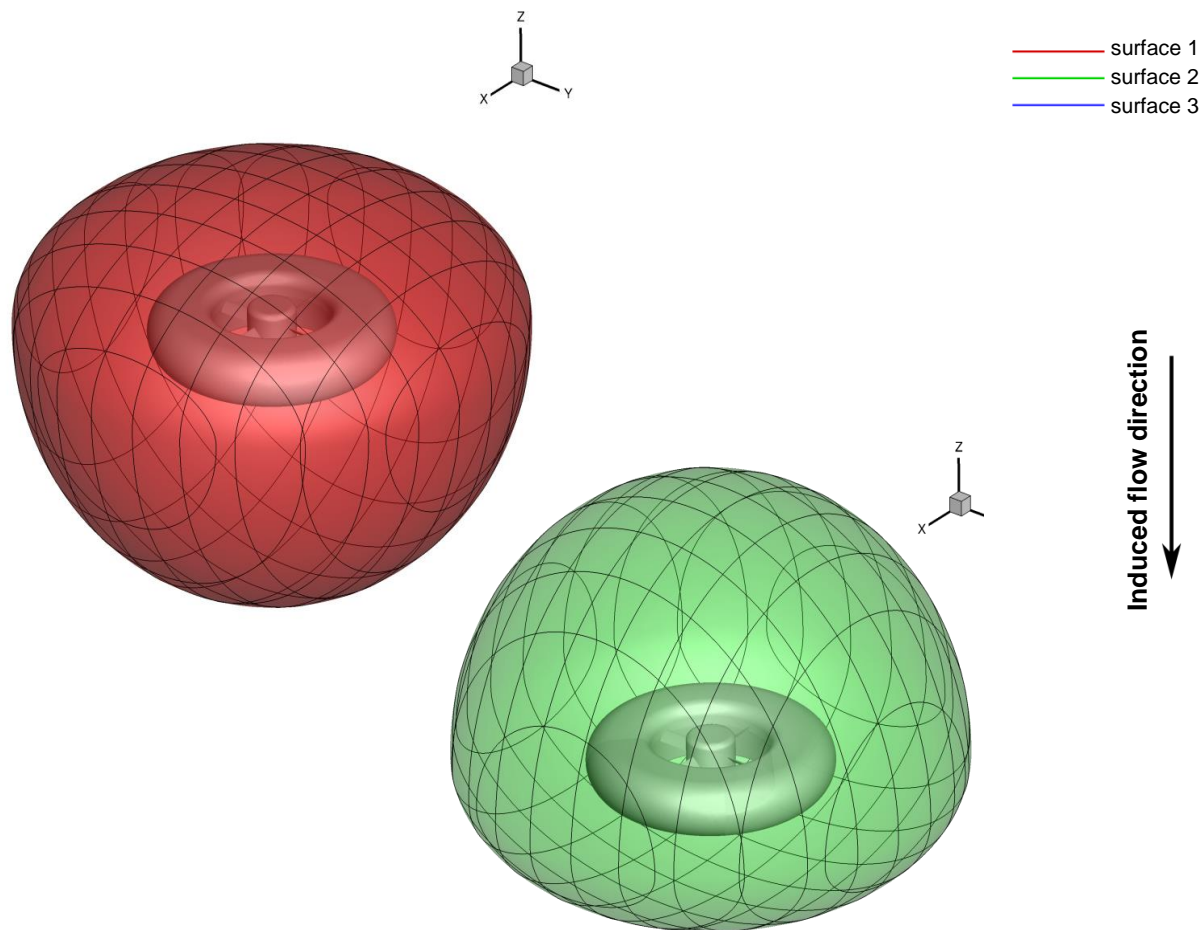
Polar graph (thrust coefficient against torque coefficient)

Kamov shrouded rotor: velocity field



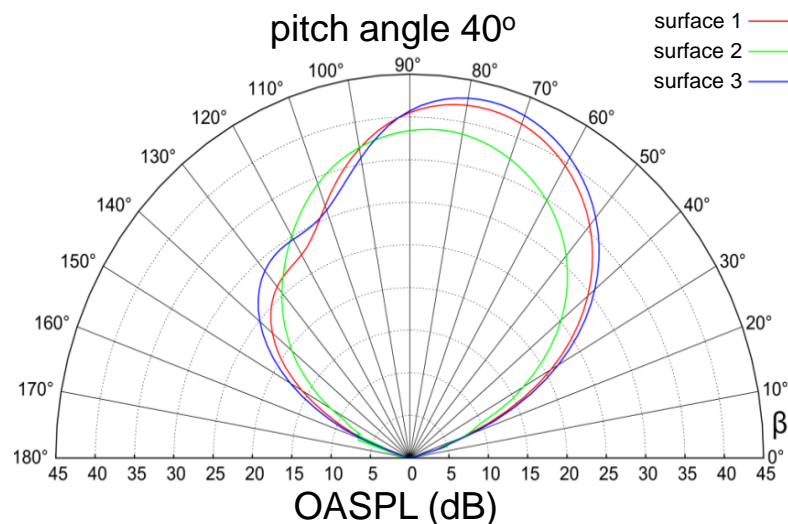
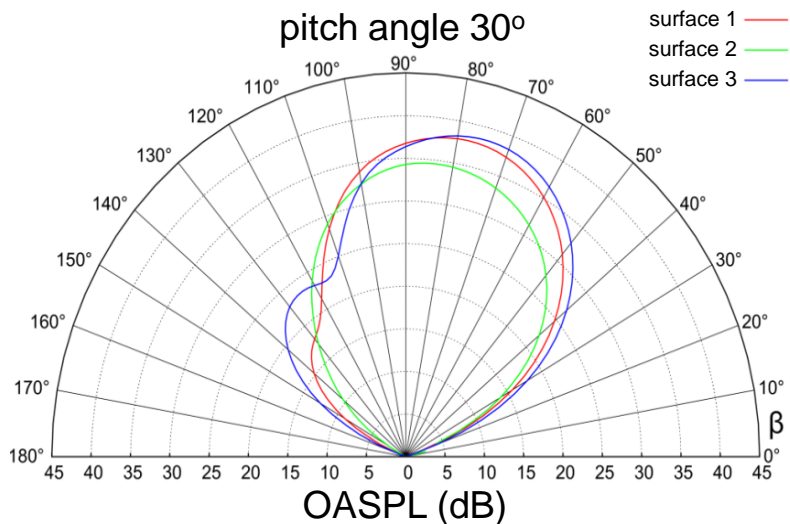
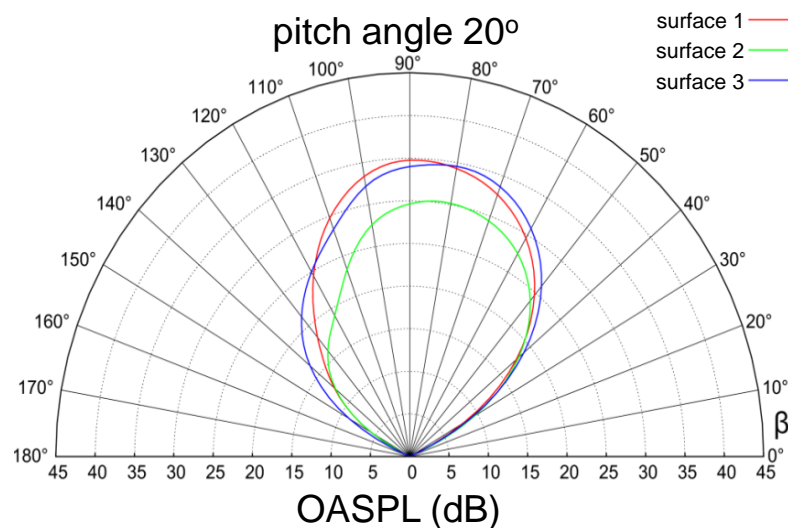
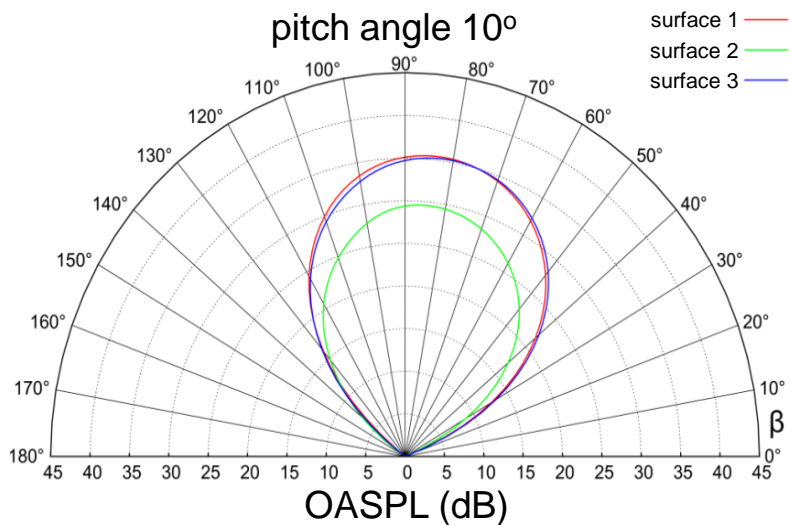
Absolute velocity fields for the pitch angles

Kamov shrouded rotor: acoustics



FWH control surfaces

Kamov shrouded rotor: acoustics



Overall sound pressure level diagrams

KAMOV SCALED MAIN ROTOR

Kamov shrouded rotor: problem setup



Blades count N	4
Rotor radius R	1.952 m
Blade chord b	0.18 m
Blade base profile	5 unsymmetrical profiles + tapered tip
Pitch angle	8°
Rotation speed	584.5 RPM
Blade tip velocity V_{tip}	119.5 m/s

$$\rho_0 = 1.193 \text{ kg/m}^3, \mu_0 = 1.822027 \times 10^{-5} \text{ N} \cdot \text{s/m}^2$$

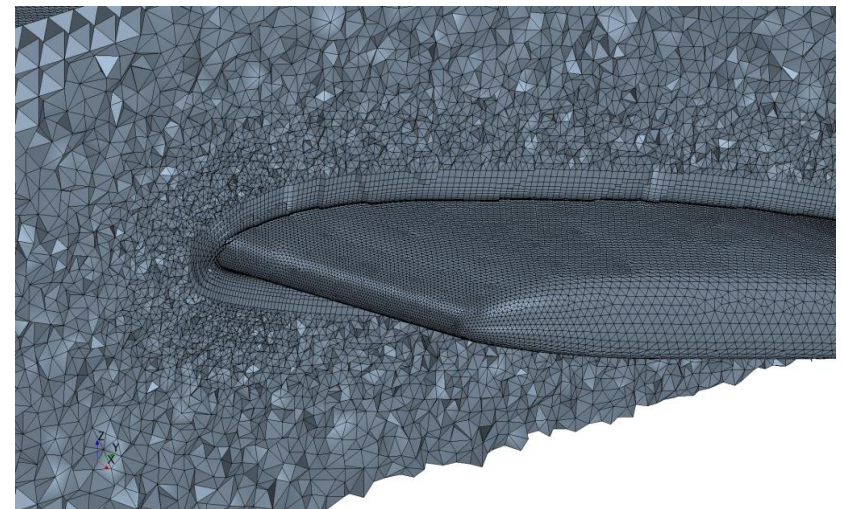
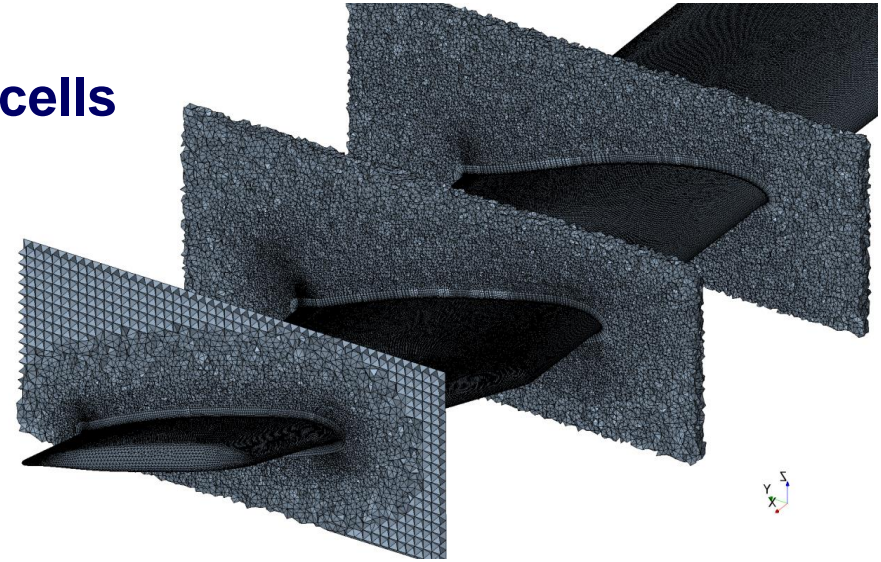
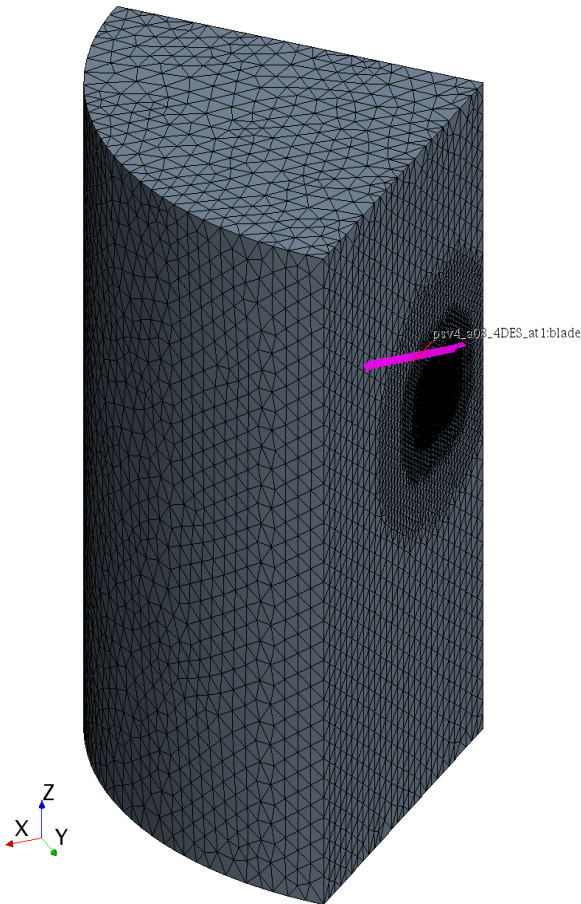
$$\text{Re} = \frac{\rho_0 V_{tip} b}{\mu_0} \approx 1.4 \times 10^6$$

Kamov shrouded rotor: problem setup

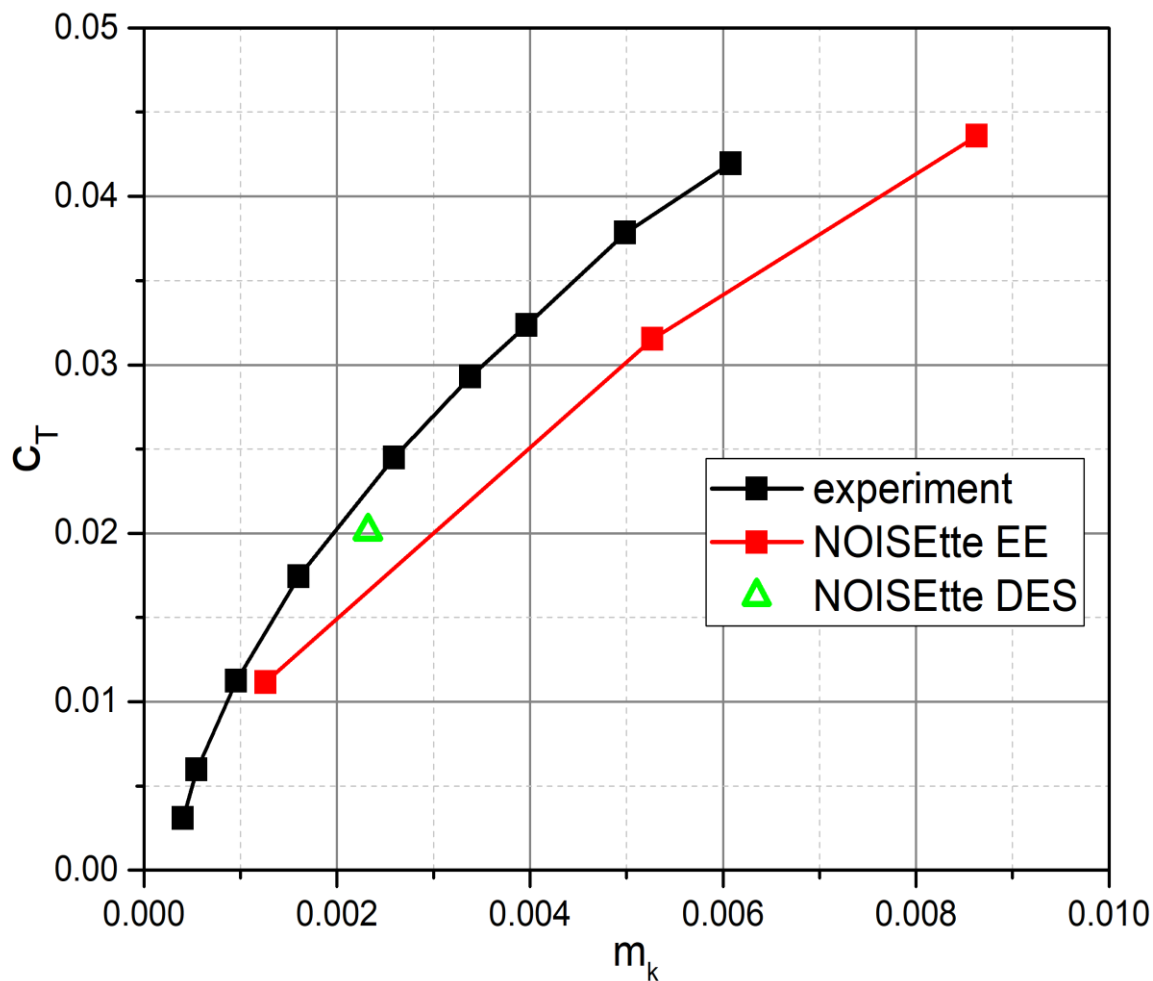
Hybrid mesh:

Single sector: 19M nodes, 99M cells

Full configuration: 75M nodes, 392M cells

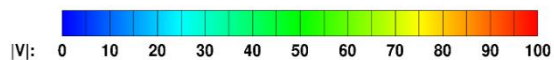
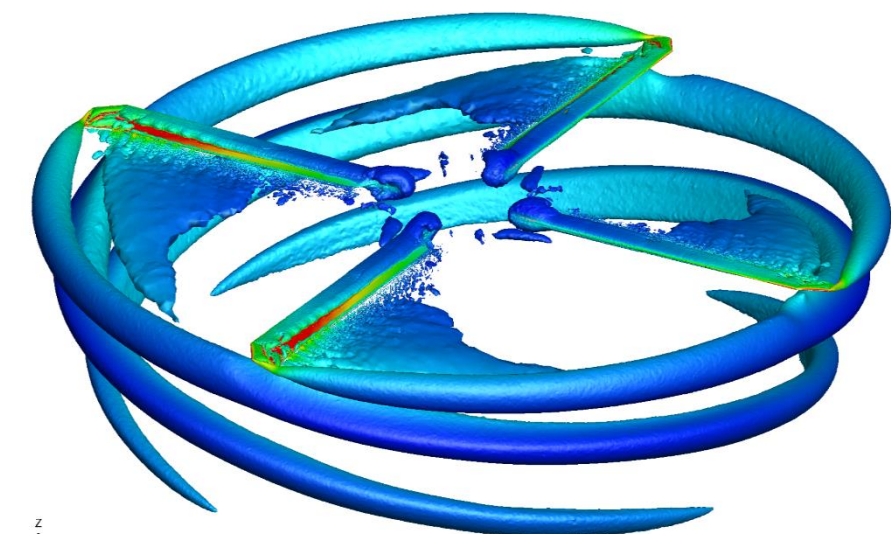


Kamov shrouded rotor: aerodynamics

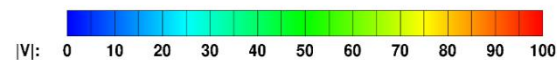
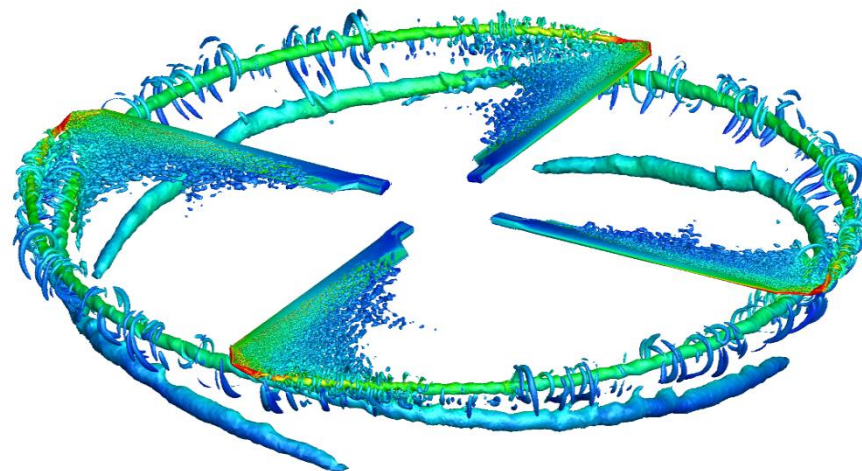


Polar graph (thrust coefficient against torque coefficient)

Kamov shrouded rotor: vortices structure

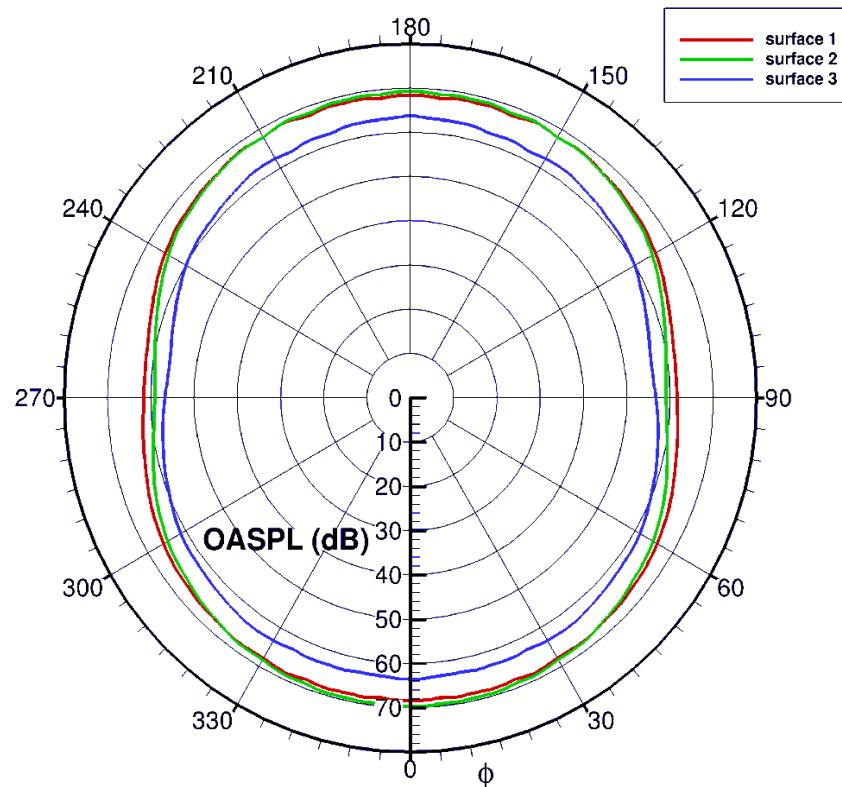
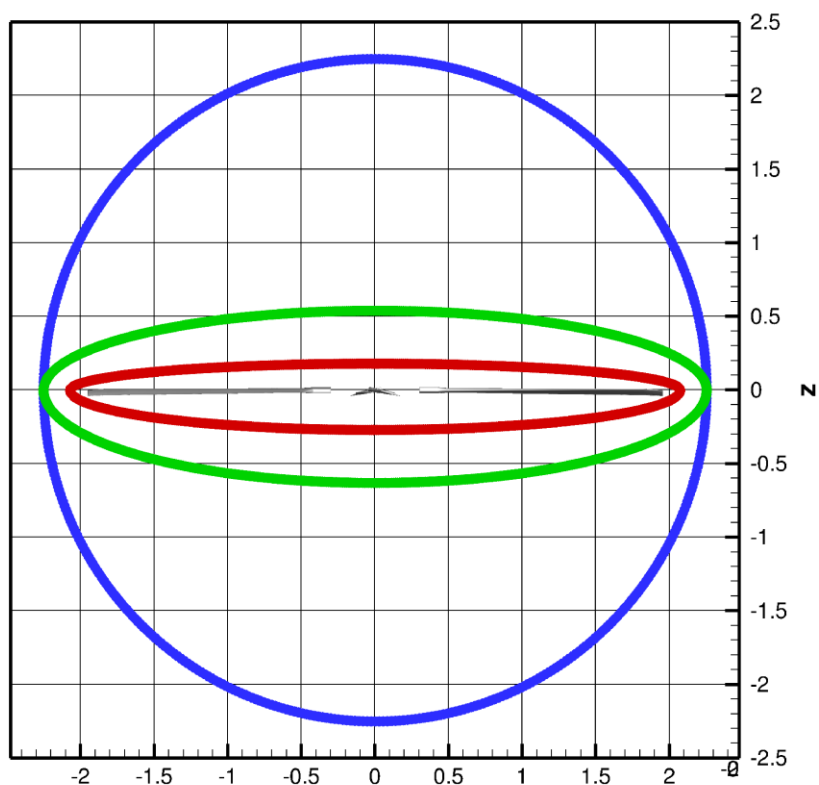


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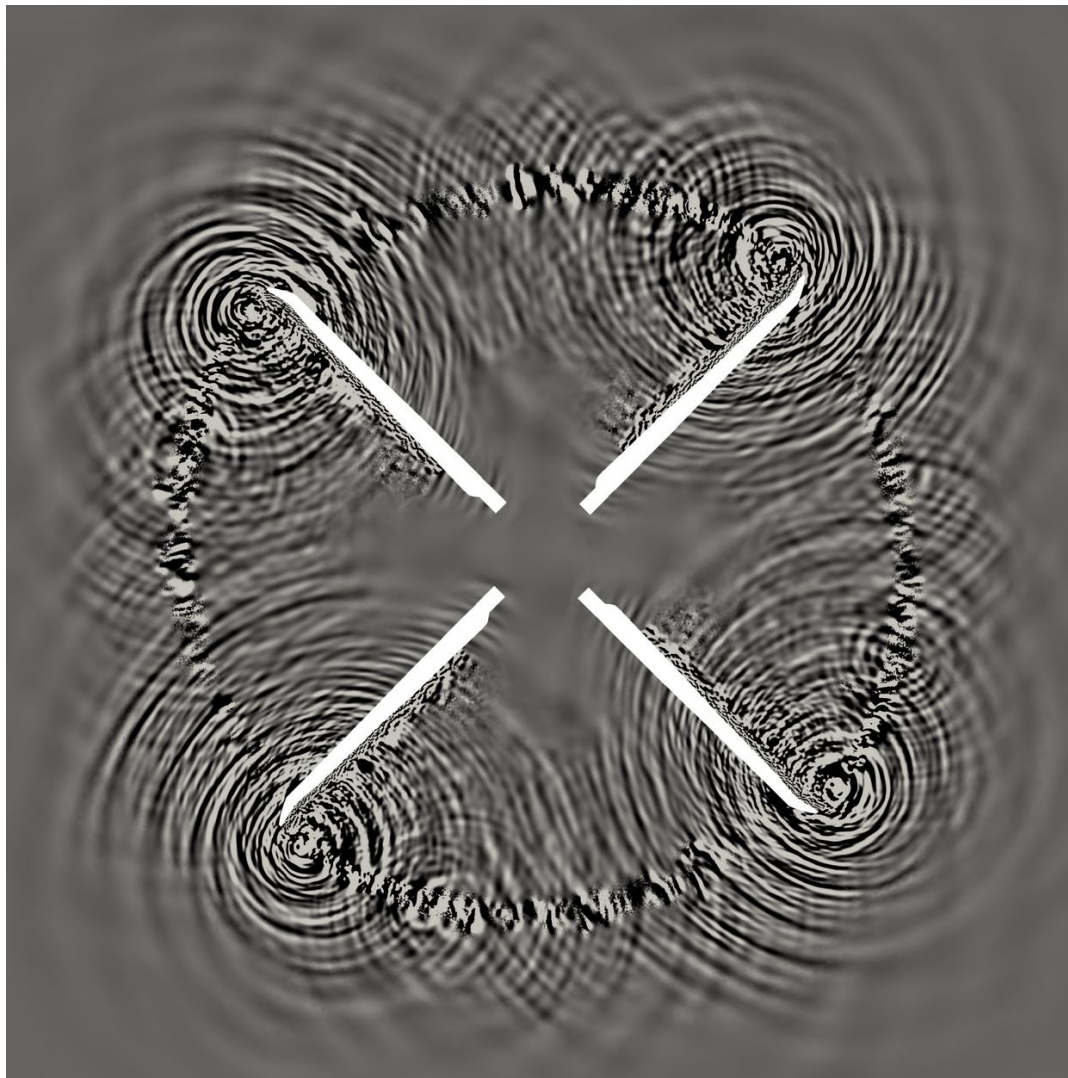
NOISEtte DES SA

Kamov shrouded rotor: acoustics



FWH control surfaces (left) and OASPLs (right)

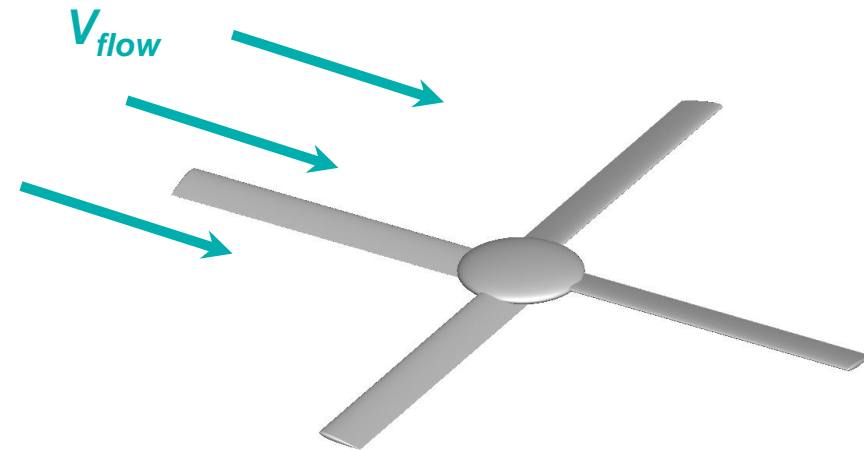
Kamov shrouded rotor: acoustics



Density gradient field in rotor plane section

PAVLOV SCALED MAIN ROTOR

PAVLOV scaled main rotor: problem setup



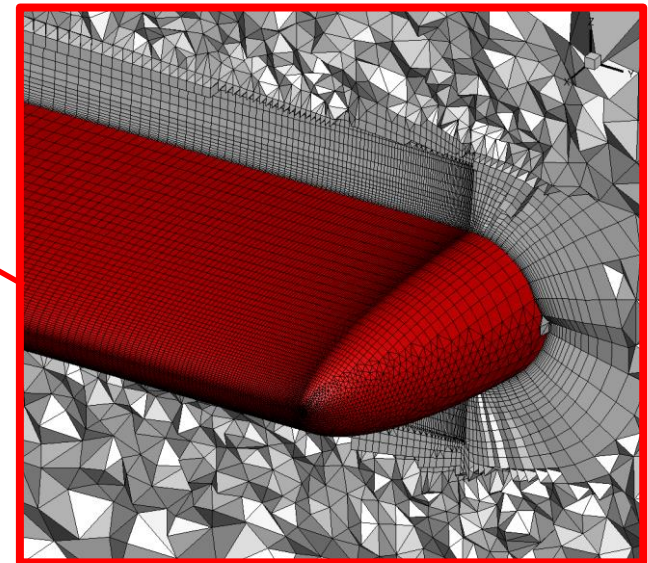
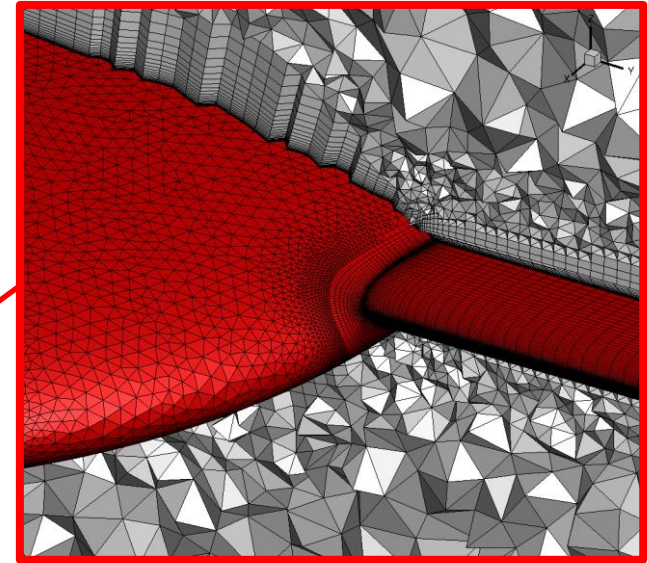
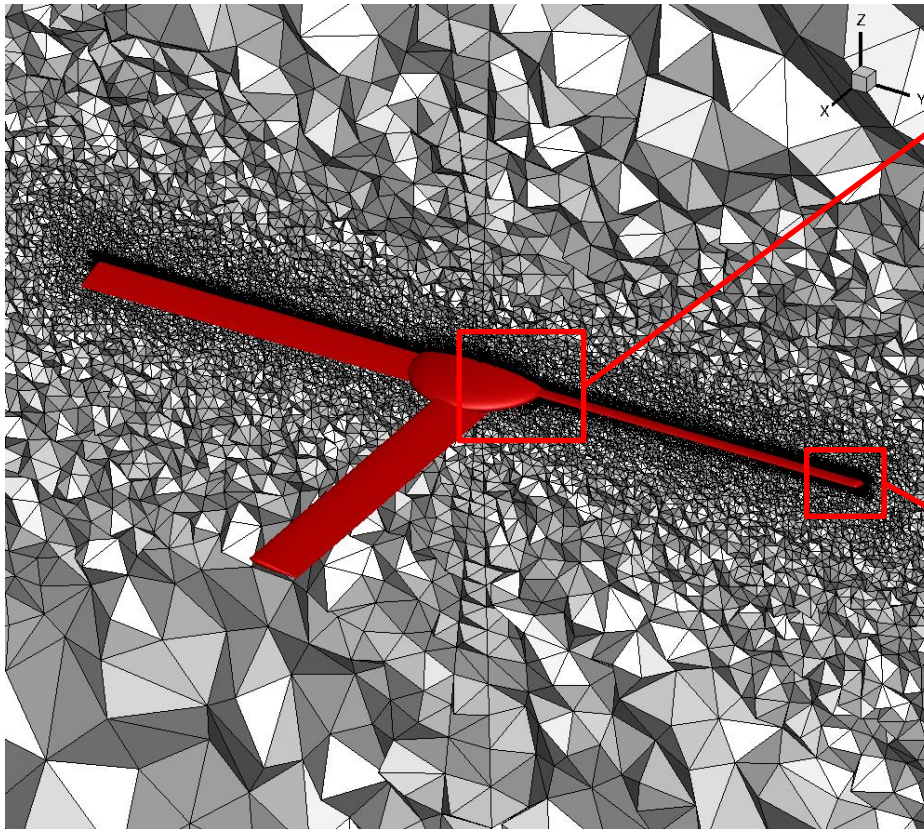
Blades count N	4
Rotor radius R	1.2 m
Blade chord b	0.15 m
Blade base profile	NACA 0012
Pitch angle	8°
Rotation speed	360 RPM
Blade tip velocity V_{tip}	45.2 m/s
Background flow V_{flow}	6.8, 11.3 m/s

$$\rho_0 = 1.225 \text{ kg/m}^3, \mu_0 = 1.827 \times 10^{-5} \text{ N} \cdot \text{s/m}^2, Re = \frac{\rho_0 V_{tip} b}{\mu_0} \approx 0.6 \times 10^6$$

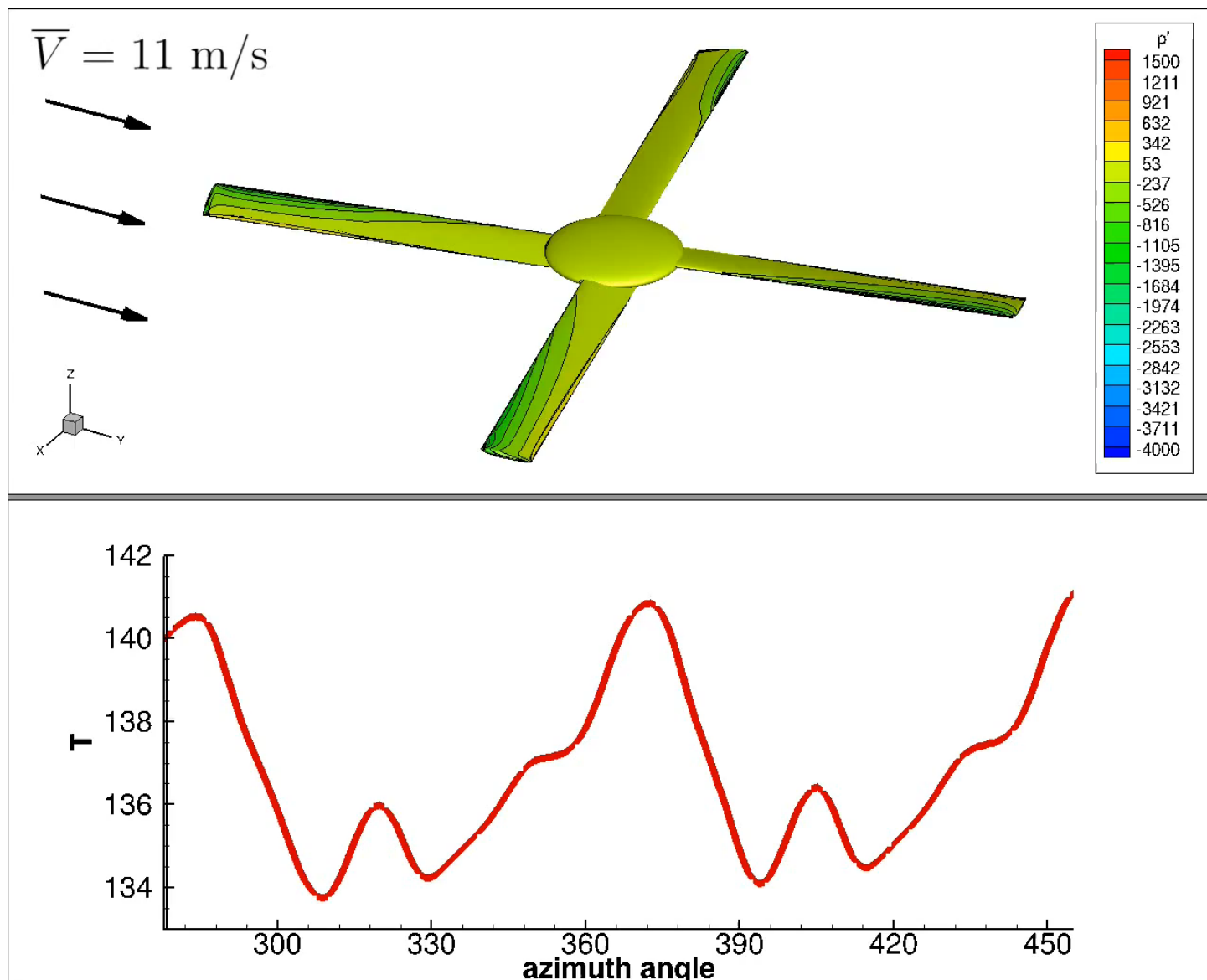
PAVLOV scaled main rotor: mesh

Hybrid mesh:

9 272 990 nodes
24 283 736 cells

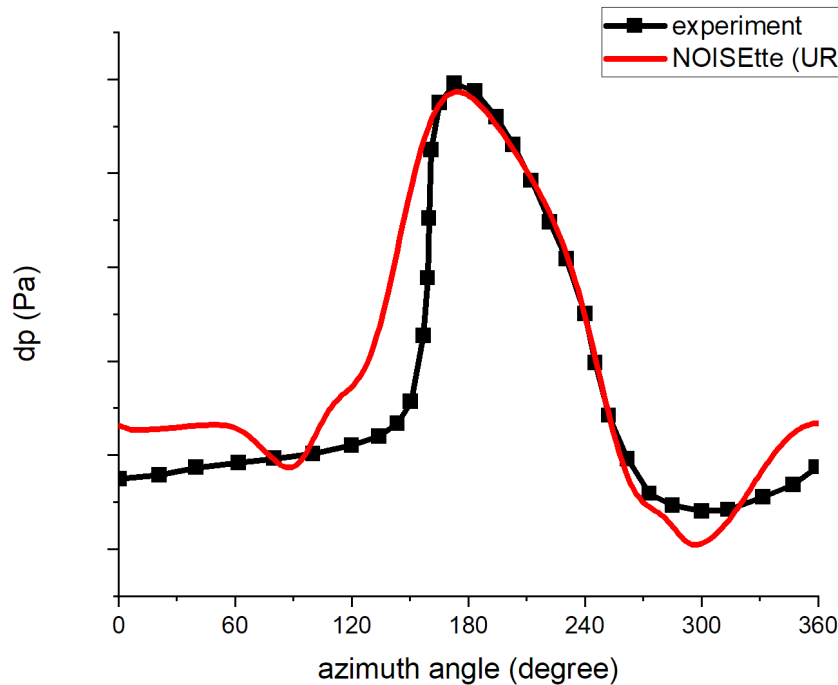
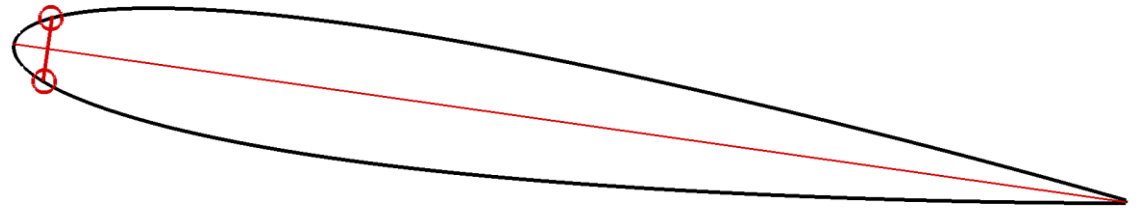


PAVLOV scaled main rotor: aerodynamics

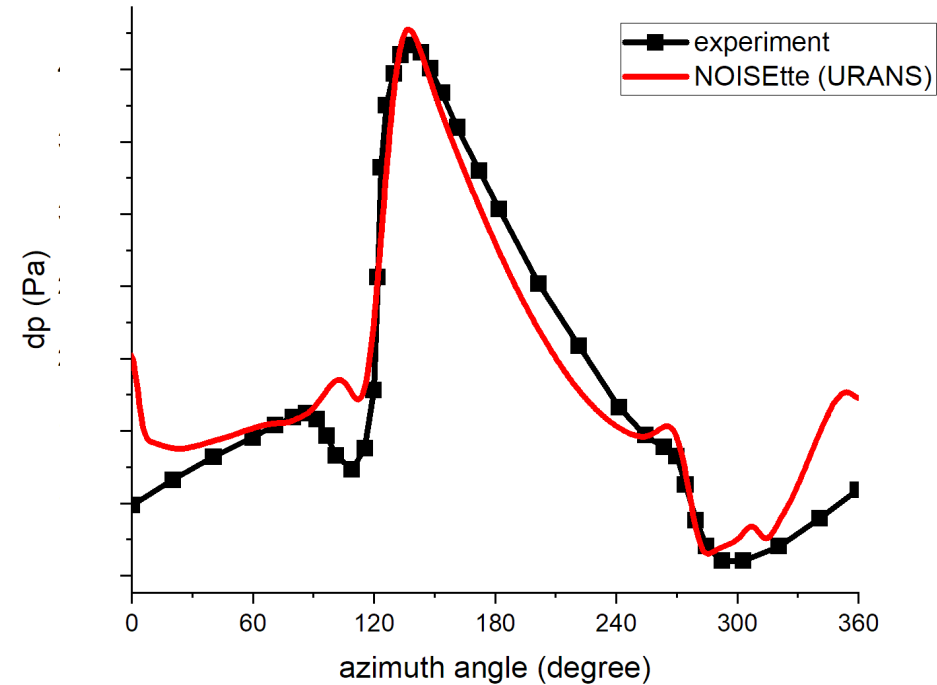


PAVLOV scaled main rotor: aerodynamics

$r/R=0.8$: $dp=p_{\text{point1}} - p_{\text{point2}}$



$V_{\text{flow}} = 6.8 \text{ m/s}$



$V_{\text{flow}} = 11.3 \text{ m/s}$

CONCLUSION

Results

- Helicopter
- Model
- aerodynamic
- The
- Star



Future work

- Dynamic change of blades pitch angle (deformable meshes, sliding meshes)
- Rotor broadband noise analysis and verification

Thank you!

Any questions?

Mathematical model and numerical method

- Navier-Stokes equations in rotating frame reference¹
- SA RANS + wall law (wall functions)²
- Hybrid turbulent model SA DDES ($\Delta = \Delta_{SLA}$ – Shear Layer Adapted)³
- Modified «1A» Farassat formulation for FWH equation⁴

¹ Abalakin, I.V., Anikin, V.A., Bakhvalov, P.A. et al. *Fluid Dyn.* (2016) 51: 419.

<https://doi.org/10.1134/S0015462816030145>

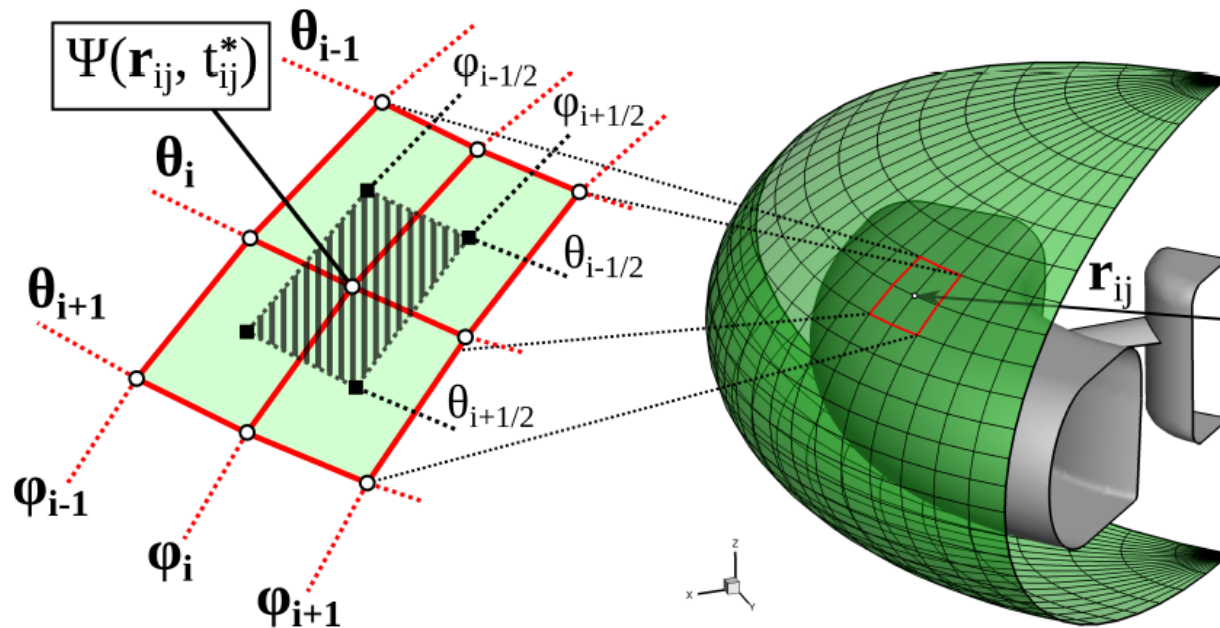
² Knopp T. Universal Wall Functions for Aerodynamic Flows: Turbulence Model Consistent Design, Potential and Limitations In book: MEGADESIGN and MegaOpt, NNFM 107, 55-71

³ Shur M., Spalart P., Strelets M., Travin A. An Enhanced Version of DES with Rapid Transition from RANS to LES in Separated Flows // *Flow Turb. Comb.*, 2015, **95**(4), 709-737

⁴ Bakhvalov, P.A., Bobkov, V.G. & Kozubskaya, T.K. *Math. Models Comput. Simul.* (2017) 9: 716.

<https://doi.org/10.1134/S2070048217060035>

FWH



$$p'(\mathbf{R}, T) = \frac{1}{4\pi} \int_{S_0} \Psi(\mathbf{r}, t^*) ds = \frac{1}{4\pi} \int \int \Psi(\mathbf{r}, t^*) r^2(\theta) \cos \theta d\theta d\phi \approx$$

$$\approx \frac{1}{4\pi} \sum_{i=0}^{N_\theta} \sum_{j=0}^{N_\phi} \Psi(\mathbf{r}_{ij}, t_{ij}^*) r_{ij}^2 (\sin \theta_{i+1/2} - \sin \theta_{i-1/2}) (\phi_{j+1/2} - \phi_{j-1/2})$$

Bakhvalov, P.A., Bobkov, V.G. & Kozubskaya, T.K. Math Models Comput. Simul. (2017) 9: 716.
<https://doi.org/10.1134/S2070048217060035>

Граничные условия

Граничные условия на поверхности

условия прилипания

на вращающейся поверхности лопасти



$$\mathbf{u} - \boldsymbol{\omega} \times \mathbf{r} = 0$$

Граничные условия на внешней границе

Задание **расщеплённых** по нормальному по направлению к границе характеристических скоростей **потоков**, связывающих значения газодинамических параметров внутри расчётной области \mathbf{U}_i , и их значений в удалённом потоке \mathbf{U}_∞ .

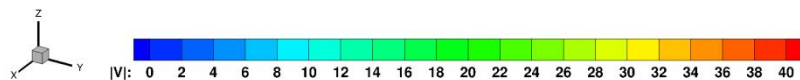
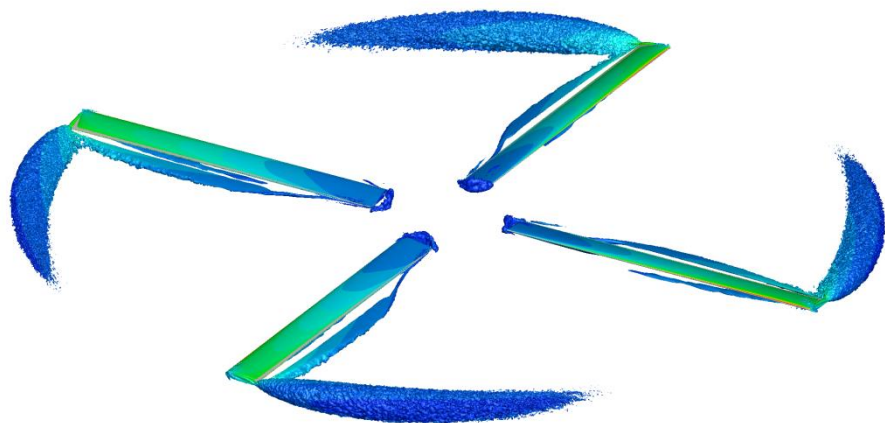
$$\mathbf{F}_B(\mathbf{U}_i, \mathbf{U}_\infty) = \mathbf{F}^+ + \mathbf{F}^- = \mathbf{A}^- \mathbf{U}_\infty + \mathbf{A}^+ \mathbf{U}_i, \quad \text{с.з.} (\mathbf{A}^\pm) = \frac{1}{2} (u_n \pm |u_n|, (u_n + c) \pm |u_n + c|, (u_n - c) \pm |u_n - c|)$$

Значения \mathbf{U}_∞ определяются характеристическими соотношениями для изэнтропического газа

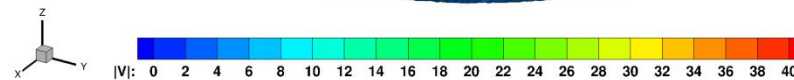
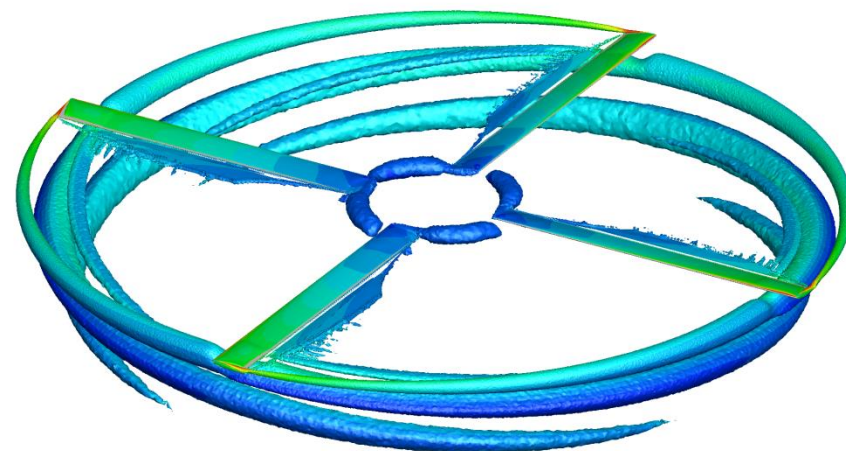
$$p_\infty = p_0 \quad \rho_\infty = \rho_i \left(\frac{p_\infty}{p_i} \right)^{1/\gamma} \quad \mathbf{U}_\infty = \mathbf{U}_i + \frac{2}{\gamma - 1} \left[\left(\gamma \frac{p_i}{\rho_i} \right)^{1/2} - \left(\gamma \frac{p_\infty}{\rho_\infty} \right)^{1/2} \right] \cdot \mathbf{n}$$

p_0 — статическое давление невозмущённого газа
 \mathbf{n} — внешняя нормаль к поверхности внешней границы

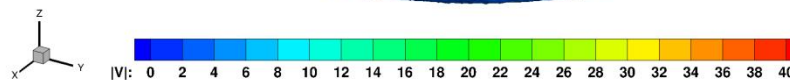
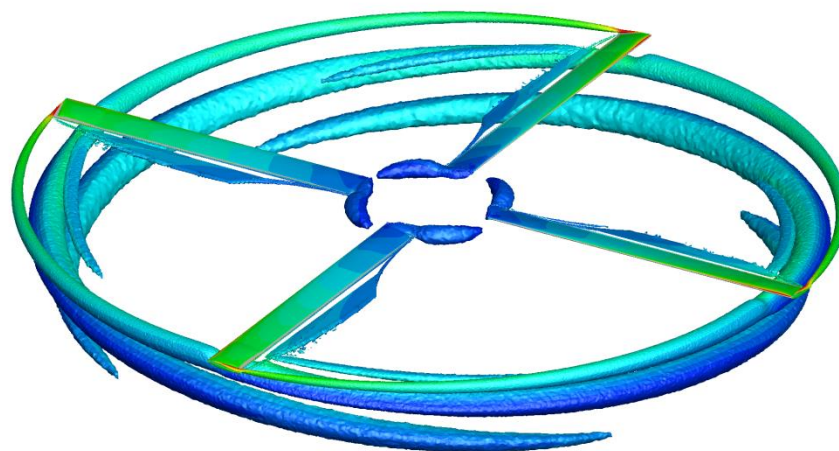
KAI scaled main rotor: order and accuracy



1st order



EBR3



EBR5